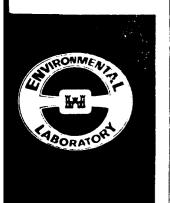


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USER GUIDE FOR WIFM-SAL: A TWO-DIMENSIONAL VERTICALLY INTEGRATED, TIME-VARYING ESTUARINE TRANSPORT MODEL

by

Richard A. Schmalz, Jr.

Hydraulics Laboratory

DEPARTMENT OF THE ARMY
Waterways Experiment Station, Corps of Engineers
PO Box 631
Vicksburg, Mississippi 39180-0631



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WIFM-SAL is preliminary to the development of comprehensive water quality

models that may be used to assist in the analysis of water quality problems in shallow estuaries and embayments which may be considered vertically well mixed. The model is two dimensional in the horizontal and generates time-varying water surface elevations, velocities, and constituent fields over a space staggered grid. Units of measure are expressed in the English system (slug-ft-second).

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20. ABSTRACT (Continued).

Results computed on a global grid may be employed as boundary conditions on a more spatially limited refined grid concentrated around the area of interest. In addition, the user may select either of two distinct transport schemes. Scheme 1 is a flux-corrected transport scheme capable of resolving sharp fronts without oscillation. Scheme 2 is a full, three time level scheme directly compatible with the three time level hydrodynamics. The telescoping grid capability in conjunction with the user selectable constituent transport scheme is an extremely powerful concept in real world transport problem solving.

Flooding Model); WES (Watering Coperant Station); Computered Simulation; Salenty; Subsortines; Input; output.

PREFACE

This report describes the development and application of a numerical transport model used as a basis for 2-D vertically averaged estuarine water quality models. The preparation of this report was sponsored by the Office, Chief of Engineers (OCE), under the Environmental Impact Research Program (EIRP). The Mobile District, CE, sponsored the Mississippi Sound Study, which is presented as a test application. Technical Monitors for EIRP were Dr. John Bushman and Mr. Earl Eiker of OCE and Mr. David B. Mathis, U. S. Army Water Resources Support Center.

The work presented in the report was conducted from July 1979 through June 1983 in the Wave Dynamics Division (WDD) of the Hydraulics Laboratory (HL) of the U. S. Army Engineer Waterways Experiment Station (WES) under the general supervision of Messrs. H. B. Simmons, Chief, HL, and Claude E. Chatham, Jr., Acting Chief, WDD. The WDD was transferred to the Coastal Engineering Research Center (CERC) of WES on 1 July 1983. From July through September 1983, work was performed in the WDD of CERC under the general supervision of Dr. R. W. Whalin, Chief, CERC, and Mr. Chatham, Chief, WDD. Dr. R. A. Schmalz, Jr., WDD, conducted the Mississippi Sound Study and prepared this report.

The preparation of this report was monitored by Mr. Ross W. Hall, Ecosystem Research and Simulation Division (ERSD), Environmental Laboratory (EL), under the general supervision of Mr. Don L. Robey, Chief, ERSD, and Dr. John Harrison, Chief, EL. Program Manager at WES for EIRP was Dr. Roger T. Saucier.

Commanders and Directors of WES during the conduct of this study and the preparation and publication of this report were COL Nelson P. Conover, CE, and COL Tilford C. Creel, CE. Technical Director was Mr. F. R. Brown.

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CONVERSION FACTORS, U. S. CUSTOMARY TO METRIC (SI) UNITS OF MEASUREMENT

t. S. customary units of measurement used in this report can be converted to metric (SI) units as follows:

Multiply	Ву	To Obtain
teet	0.3048	metres
teet per second	0.3048	metres per second
miles per hour (U.S. statute)	1.609347	kilometres per hour

USER GUIDE FOR WIFM-SAL: A TWO-DIMENSIONAL VERTICALLY INTEGRATED, TIME-VARYING ESTUARINE TRANSPORT MODEL

PART I: CAPABILITIES AND LIMITATIONS

- 1. The transport model WIFM-SAL was developed as a prerequisite requirement for water quality models to be used in the analysis of water quality problems in shallow estuaries and embayments which may be considered vertically well mixed thereby justifying a vertically integrated approach. The model is two-dimensional in the horizontal and generates time-varying water surface elevations, velocities, and constituent fields over a space staggered grid. Units of measure are expressed in the English system (slug-foot-second).
- 2. Two constituent transport schemes have been incorporated in the U. S. Army Engineer Waterways Experiment Station (WES) Implicit Flooding Model (WIFM) developed by Butler (1980). Constituent computations are performed at the same time step interval as employed in the hydrodynamic computations. Therefore, if desired, the user may develop the coding necessary to density couple the hydrodynamics if this is important for the problem of concern. Density coupling is not implemented in the model at this time.
- 3. An exponentially stretched grid system is used in WIFM-SAL allowing the user to increase resolution in specific areas where more computational detail is desired. This feature is particularly useful in modeling inlets and barrier island systems.
- 4. Since the constituent transport schemes are directly encoded within WIFM, this model must be used to provide the hydrodynamic description. Future work will be conducted to develop a separate transport-dispersion model, allowing for user selectable hydrodynamic input and transport scheme selection.
- 5. Although WIFM has been used extensively in moving boundary applications, the transport schemes assume a fixed land/sea boundary. Future work is needed to remove this restriction.
- 6. The constituent transport equation considered is for a passive scalar without source/sink terms. The extension to multiple (reacting) constituent systems remains to be developed.
- 7. WIFM-SAL allows the model user to employ results computed on a global grid as boundary conditions on a more spatially limited, refined grid

concentrated around the area of interest. In addition, the user may select either of two distinct transport schemes. Scheme 1 is a flux-corrected transport scheme capable of resolving sharp fronts without oscillation. Scheme 2 is a full, three time level scheme directly compatible with the three time level hydrodynamics. Scheme 1 requires approximately three times more computer time than scheme 2 but is more accurate than scheme 2 for sharp front problems.

8. However, on a coarse spatial resolution global grid covering a large area, scheme 2 results may be used in areas away from sharp fronts to provide boundary conditions for a more refined grid system encompassing the sharp front region of propagation. Scheme 1 may then be selected to resolve the sharp front over this refined grid. Thus, the telescoping grid capability in conjunction with the user selectable constituent transport scheme is an extremely powerful concept in real world transport problem solving.

PART II: THEORETICAL DEVELOPMENTS

9. Consider the instantaneous three-dimensional constituent transport equation. The time scales for which this equation applies are of much shorter duration than can be modeled. Therefore, the instantaneous equation is temporally averaged. Under the vertically integrated approach, the resulting equation is then depth averaged. The transport equation obtained is then transformed using an exponential stretch. Numerical approximations to the transformed equation are formulated followed by the development of relations for the effective dispersion coefficients.

Constituent Transport Equation in Cartesian Coordinates

10. The instantaneous constituent transport equation is

$$\frac{\partial s}{\partial t} + u \frac{\partial s}{\partial x} + v \frac{\partial s}{\partial y} + w \frac{\partial s}{\partial z} = \frac{\partial}{\partial x} \left(D_x \frac{\partial s}{\partial x} \right) + \frac{\partial}{\partial z} \left(D_y \frac{\partial s}{\partial y} \right) + \frac{\partial}{\partial z} \left(D_z \frac{\partial s}{\partial z} \right)$$
(1)

where

 $x,y,z \equiv Cartesian coordinates$

 $u,v,w \equiv velocity components in the x-, y-, and z-directions, respectively$

t ≡ time

 $s \equiv concentration of the material of concern$

 $D_{y} \equiv molecular diffusion coefficient in the x-direction$

 D_{v} = molecular diffusion coefficient in the y-direction

 D_{z} = molecular diffusion coefficient in the z-direction

For a turbulent flow, the turbulent diffusion is much greater than the molecular diffusion. The following analogous formula holds where time averaging over the time scale of the turbulence has been performed.

$$\frac{\partial s}{\partial t} + u \frac{\partial s}{\partial x} + v \frac{\partial s}{\partial y} + w \frac{\partial s}{\partial z} = \frac{\partial}{\partial x} \left(K_x \frac{\partial s}{\partial x} \right) + \frac{\partial}{\partial z} \left(K_y \frac{\partial s}{\partial y} \right) + \frac{\partial}{\partial z} \left(K_z \frac{\partial s}{\partial z} \right)$$
(2)

where K_x , K_y , and K_z are turbulent diffusion coefficients. Equation 2 may be written in conservation form by adding s times the continuity equation (namely, zero) to the left-hand side to obtain

$$\frac{\partial s}{\partial t} + \frac{\partial (us)}{\partial x} + \frac{\partial (vs)}{\partial y} + \frac{\partial (ws)}{\partial z}$$

$$= \frac{\partial}{\partial x} \left(K_x \frac{\partial s}{\partial x} \right) + \frac{\partial}{\partial y} \left(K_y \frac{\partial s}{\partial y} \right) + \frac{\partial}{\partial z} \left(K_z \frac{\partial s}{\partial z} \right)$$
(3)

This form of the equation is then depth integrated as described in Schmalz (1981a) to obtain:

$$\frac{\partial}{\partial t} (hs) + \frac{\partial}{\partial x} (hus) + \frac{\partial}{\partial y} (hvs) = \frac{\partial}{\partial x} \left(hK_x^* \frac{\partial s}{\partial x} \right) + \frac{\partial}{\partial y} \left(hK_y^* \frac{\partial s}{\partial y} \right)$$
(4)

where h is the water depth and $K_{\mathbf{X}}^{*}$ and $K_{\mathbf{Y}}^{*}$ are effective dispersion coefficients.

Constituent Transport Equation in Transformed Coordinates

11. The transport equation is transformed from x - y space to α_1 - α_2 space by means of the following coordinate transformation as considered by Butler (1980).

$$x = a_1 + b_1 \alpha_1^{c_1} \Longrightarrow \alpha_1 = \left(\frac{x - a_1}{b_1}\right)^{1/c_1}$$
 (5)

$$y = a_2 + b_2 \alpha_2^{c_2} \Longrightarrow \alpha_2 = \left(\frac{y - a_2}{b_2}\right)^{1/c_2}$$
 (6)

The terms a_1 , b_1 , c_1 , a_2 , b_2 , and c_2 are constants valid for different regions in the grid. Then for an arbitrary hydrodynamic variable $\rho(x,y,t)$

$$\frac{\partial \rho}{\partial x} = \frac{\partial \rho}{\partial \alpha_1} \frac{d\alpha_1}{dx} \qquad \frac{\partial \rho}{\partial y} = \frac{\partial \rho}{\partial \alpha_2} \frac{d\alpha_2}{dy} \tag{7}$$

$$\frac{\partial^2 \rho}{\partial x^2} = \frac{\partial}{\partial \alpha_1} \left(\frac{\partial \rho}{\partial x} \right) \frac{d\alpha_1}{dx} = \frac{\partial}{\partial \alpha_1} \left(\frac{\partial \rho}{\partial \alpha_1} \frac{d\alpha_1}{dx} \right) \frac{d\alpha_1}{dx} = \frac{d\alpha_1}{dx} \left[\frac{\partial^2 \rho}{\partial \alpha_1^2} \frac{d\alpha_1}{dx} + \frac{\partial \rho}{\partial \alpha_1} \frac{\partial}{\partial \alpha_1} \left(\frac{d\alpha_1}{dx} \right) \right]$$
(8a)

$$\frac{\partial^{2} \rho}{\partial y^{2}} = \frac{\partial}{\partial \alpha_{2}} \left(\frac{\partial \rho}{\partial y} \right) \frac{d\alpha_{2}}{dy} = \frac{\partial}{\partial \alpha_{2}} \left(\frac{\partial \rho}{\partial \alpha_{2}} \frac{d\alpha_{2}}{dy} \right) \frac{d\alpha_{2}}{dy} = \frac{d\alpha_{2}}{dy} \left[\frac{\partial^{2} \rho}{\partial \alpha_{2}} \frac{d\alpha_{2}}{dy} + \frac{\partial \rho}{\partial \alpha_{2}} \frac{\partial}{\partial \alpha_{2}} \left(\frac{d\alpha_{2}}{dy} \right) \right]$$
(8b)

If we introduce $\mu_1 = dx/d\alpha_1$ and $\mu_2 = dy/d\alpha_2$ then

$$\frac{\partial \rho}{\partial x} = \frac{1}{\mu_1} \frac{\partial \rho}{\partial \alpha_1} \qquad \frac{\partial \rho}{\partial y} = \frac{1}{\mu_2} \frac{\partial \rho}{\partial \alpha_2}$$
 (9)

$$\frac{\partial^2 \rho}{\partial x^2} = \frac{1}{\mu_1} \left[\frac{1}{\mu_1} \frac{\partial^2 \rho}{\partial \alpha_1^2} + \frac{\partial \rho}{\partial \alpha_1} \frac{\partial}{\partial \alpha_1} \left(\frac{1}{\mu_1} \right) \right]$$
(10)

$$\frac{\partial^2 \rho}{\partial y^2} = \frac{1}{\mu_2} \left[\frac{1}{\mu_2} \frac{\partial^2 \rho}{\partial \alpha_2^2} + \frac{\partial \rho}{\partial \alpha_2} \frac{\partial}{\partial \alpha_2} \left(\frac{1}{\mu_2} \right) \right]$$
(11)

Considering Equation 8a in an alternate manner

$$\frac{\partial^2 \rho}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial \rho}{\partial \alpha_1} \frac{d\alpha_1}{dx} \right) = \frac{\partial}{\partial x} \left(\frac{\partial \rho}{\partial \alpha_1} \right) \frac{d\alpha_1}{dx} + \frac{\partial \rho}{\partial \alpha_1} \frac{d^2 \alpha_1}{dx^2}$$
 (12)

Noting $\partial/\partial x = (\partial/\partial\alpha_1)(d\alpha_1/dx) = (\partial/\partial\alpha_1)(1/\mu_1)$

$$\frac{\partial^2 \rho}{\partial x^2} = \frac{\partial^2 \rho}{\partial \alpha_1^2} \left(\frac{d\alpha_1}{dx}\right)^2 + \frac{\partial \rho}{\partial \alpha_1} \frac{d^2 \alpha_1}{dx^2}$$
 (13)

Employing previous notation, Equation 13 is rewritten as follows:

$$\frac{\partial^2 \rho}{\partial x^2} = \frac{\partial^2 \rho}{\partial \alpha_1^2} \left(\frac{1}{\mu_1}\right)^2 + \frac{\partial \rho}{\partial \alpha_1} \frac{d}{dx} \left(\frac{1}{\mu_1}\right)$$
 (14)

Note, however, from the relation between $\partial/\partial x$ and $\partial/\partial \alpha_1$ we obtain

$$\frac{\partial^2 \rho}{\partial x^2} = \frac{\partial^2 \rho}{\partial \alpha_1^2} \left(\frac{1}{\mu_1}\right)^2 + \frac{\partial \rho}{\partial \alpha_1} \frac{d}{d\alpha_1} \left(\frac{1}{\mu_1}\right) \frac{1}{\mu_1}$$
 (15)

This relation is equivalent to Equation 8.

12. If we consider a hydrodynamic variable $~\rho(\alpha_1^{},\alpha_2^{},t)~$ and let $~i^*$, $~j^*$, ~n~ be defined such that

$$\rho_{i*,j*}^{n} = \rho(i*\Delta\alpha_2, j*\Delta\alpha_1, n\Delta t)$$
 (16)

Then let i, j, n be such that

$$\rho_{i,j}^{n} = \rho \left[a_{2} + b_{2} (i * \Delta \alpha_{2})^{c_{2}}, \quad a_{1} + b_{1} (j * \Delta \alpha_{1})^{c_{1}}, \quad n \Delta t \right]$$
 (17)

We employ uniform spacing in α_1 - α_2 space and irregular spacing in x - y space. We may evaluate the derivatives with respect to x and y as follows.

$$\frac{\partial \rho}{\partial \mathbf{x}} \begin{vmatrix} \mathbf{n} \\ \mathbf{i}, \mathbf{j} \end{vmatrix} = \frac{\partial \rho}{\partial \alpha_1} \begin{vmatrix} \mathbf{n} & \frac{\mathbf{d}\alpha_1}{\mathbf{d}\mathbf{x}} \\ \mathbf{i}^*, \mathbf{j}^* \end{vmatrix} \mathbf{j}^*$$
(18)

where

$$\frac{d\alpha_{1}}{dx} = \frac{1}{c_{1}b_{1}} \left(\frac{x - a_{1}}{b_{1}} \right)^{(1-c_{1})/c_{1}} = f(x)$$

$$f\left(a_{1} + b_{1}\alpha_{1}^{c_{1}}\right) = \frac{1}{c_{1}b_{1}} \alpha_{1}^{(1-c_{1})} = f(\alpha_{1}) \qquad \frac{d\alpha_{1}}{dx} \Big|_{j^{*}} = f(j^{*}\Delta\alpha_{1})$$

and

$$\frac{\partial \rho}{\partial y} \begin{vmatrix} n \\ i, j \end{vmatrix} = \frac{\partial \rho}{\partial \alpha_2} \begin{vmatrix} n & \frac{d\alpha_2}{dy} \\ i^*, j^* \end{vmatrix} i^*$$
(19)

where

$$\frac{d\alpha_{2}}{dy} = \frac{1}{c_{2}b_{2}} \left(\frac{y - a_{2}}{b_{2}} \right)^{(1-c_{2})/c_{2}} = g(y)$$

$$g\left(a_{2} + b_{2}\alpha_{2}^{c_{2}}\right) = \frac{1}{c_{2}b_{2}} \alpha_{2}^{(1-c_{2})} = g(\alpha_{2}) \qquad \frac{d\alpha_{2}}{dy} \bigg|_{i = 0} = g(i * \Delta \alpha_{2})$$

For the second derivative term we obtain

$$\frac{\partial^{2} \rho}{\partial x^{2}} \Big|_{i,j}^{n} = \frac{d\alpha_{1}}{dx} \Big|_{j} \left[\frac{\partial^{2} \rho}{\partial \alpha_{1}} \Big|_{i^{*},j^{*}}^{n} \frac{d\alpha_{1}}{dx} \Big|_{j} + \frac{\partial \rho}{\partial \alpha_{1}} \Big|_{i^{*},j^{*}}^{n} \frac{d}{d\alpha_{1}} \left(\frac{d\alpha_{1}}{dx} \right) \Big|_{j^{*}} \right]$$
(20)

where

$$\frac{d}{d\alpha_1} \left(\frac{d\alpha_1}{dx} \right) = \frac{d}{d\alpha_1} \left[f \left(a_1 + b_1 \alpha_1^c \right) \right] = \frac{(1 - c_1)}{c_1 b_1} \alpha_1^{-c_1} = h(\alpha_1)$$

$$\frac{d}{d\alpha_1} \left(\frac{d\alpha_1}{dx} \right) \bigg|_{i \stackrel{*}{\sim}} = h(j \stackrel{*}{\sim} \Delta \alpha_1)$$

Similarly, for $\frac{\partial^2 \rho}{\partial y^2} \Big|_{i,j}^n$. The underlined terms in Equations 10 and 11,

although they may be computed exactly, are approximated using finite differencing on $\,\mu_1^{}\,$ and $\,\mu_2^{}\,$.

13. Transforming Equation 4 in x - y space to α_1 - α_2 space we obtain the following result:

$$(ds)_{t} + \frac{(dus)_{\alpha_{1}}}{\mu_{1}} + \frac{(dvs)_{\alpha_{2}}}{\mu_{2}} = \frac{1}{\mu_{1}} \left[dK_{\alpha_{1}} \frac{(s)_{\alpha_{1}}}{\mu_{1}} \right]_{\alpha_{1}} + \frac{1}{\mu_{2}} \left[dK_{\alpha_{2}} \frac{(s)_{\alpha_{2}}}{\mu_{2}} \right]_{\alpha_{2}}$$
(21)

where d is introduced as the depth in place of h

$$()_{t} = \partial/\partial t$$

$$()_{\alpha_{1}} = \partial/\partial\alpha_{1}$$

$$()_{\alpha_{2}} = \partial/\partial\alpha_{2}$$

Equation 21 is the relation that is the subject of numerical approximation.

Numerical Approximations

- 14. Schmalz (1983a, 1983b, 1983c) considered several alternate techniques for approximating Equation 21. The Flux Corrected Transport Scheme (FCT) was selected as the most accurate scheme and has been incorporated in the Waterways Experiment Station Implicit Flooding Model (WIFM). In addition a three time level explicit transport scheme was also incorporated in the model. A space staggered grid as shown in Figure 1 was employed in all of the formulations. The datum convention is presented in Figure 2.
- 15. Let us introduce the following notation as a prelude to the approximations. Define for an arbitrary variable $F_{n,m}^k$, where $t=k\Delta t$, $y=n\Delta y$, $x=m\Delta x$:

$$\delta_{t}^{k}(F_{n,m}^{k}) = F_{n,m}^{k+1/2} - F_{n,m}^{k}$$
 (22a)

$$\delta_{t}^{k}(F_{n,m}^{k}) = F_{n,m}^{k+1} - F_{n,m}^{k}$$
 (22b)

$$\delta_{\alpha_1}(F_{n,m}^k) = F_{n,m+1/2}^k - F_{n,m-1/2}^k$$
 (22c)

$$\delta_{\alpha_2}(F_{n,m}^k) = F_{n+1/2,m}^k - F_{n-1/2,m}^k$$
 (22d)

$$\frac{\alpha_1}{F_{n,m}} = \frac{\left(F_{n,m+1/2}^k + F_{n,m-1/2}^k\right)}{2}$$
 (22e)

$$\frac{\alpha_2}{F_{n,m}} = \frac{\left(F_{n+1/2,m}^k + F_{n-1/2,m}^k\right)}{2}$$
 (22f)

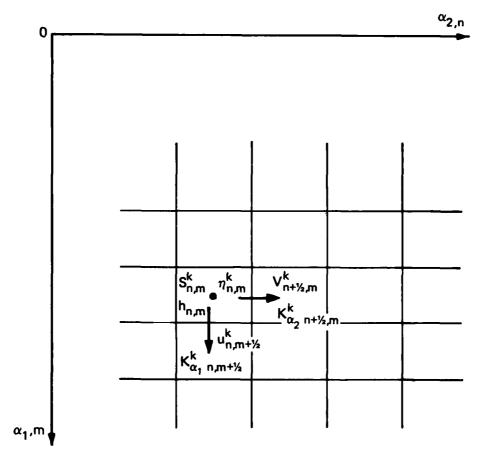
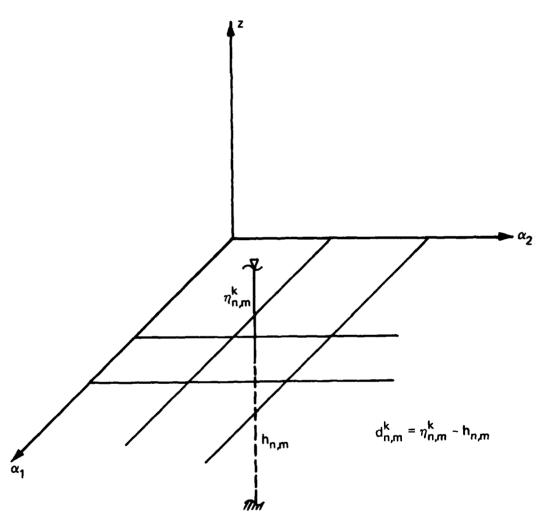


Figure 1. Space staggered finite difference grid in transformed coordinates



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Figure 2. Datum convention employed within the space staggered grid system

Flux-corrected transport scheme

- 16. Two schemes are used in implementing this approach: a lower order in space nonoscillatory scheme and a higher order in space scheme subject to oscillation. In the method implemented, two time level implicit multioperational ADI schemes were employed. The forward time upwind space (FTUS) and forward time centered space (FTCS) schemes were used as the lower and higher order in space schemes, respectively, and are discussed in turn below. Finally, the necessary flux correction procedures are developed.
- 17. <u>Leendertse FTCS multioperational scheme</u>. The following finite difference equation is considered as an approximation to the nonlinear transport equation (21):

$$\delta_{t}^{k}(ds) + \frac{\Delta t}{2\Delta\alpha_{1}(\mu_{1})_{m}} \delta_{\alpha_{1}} \left(\frac{\alpha_{1}}{d}^{k+1} + \frac{\alpha_{1}}{s}^{k+1} u^{k+1} + \frac{\alpha_{1}}{d}^{k} u^{k} \right)$$

$$+ \frac{\Delta t}{2\Delta\alpha_{2}(\mu_{2})_{n}} \delta_{\alpha_{2}} \left(\frac{\alpha_{2}}{d}^{k+1} + \frac{\alpha_{2}}{s}^{k+1} u^{k+1} + \frac{\alpha_{2}}{d}^{k} u^{k} \right)$$

$$- \frac{\Delta t}{2(\Delta\alpha_{1})^{2}(\mu_{1})_{m}} \delta_{\alpha_{1}} \left[\frac{\alpha_{1}}{d}^{k+1} K_{\alpha_{1}}^{k+1} + \frac{\alpha_{1}}{a}^{k+1} (\mu_{1})_{m}^{k+1} + \frac{\alpha_{1}}{d}^{k} K_{\alpha_{1}}^{k} + \frac{\delta_{\alpha_{1}}(s^{k})}{(\mu_{1})_{m}} \right]$$

$$- \frac{\Delta t}{2(\Delta\alpha_{2})^{2}(\mu_{2})_{n}} \delta_{\alpha_{2}} \left[\frac{\alpha_{2}}{d}^{k+1} K_{\alpha_{2}}^{k+1} + \frac{\delta_{\alpha_{2}}(s^{k+1})}{(\mu_{2})_{n}} + \frac{\alpha_{2}}{d}^{k} K_{\alpha_{2}}^{k} + \frac{\delta_{\alpha_{2}}(s^{k})}{(\mu_{2})_{n}} \right] = 0 \quad \text{at } (n,m)$$

The solution of the above semi-implicit difference scheme requires the inversion of a large unbanded matrix. In order to reduce computational effort, the following ADI multioperational difference equations are used.

18. The approximations for the X-Sweep may now be written as follows:

$$\delta_{t}^{k}(ds) + \frac{\Delta t \delta_{\alpha_{1}}}{2\Delta\alpha_{1}(\mu_{1})_{m}} \left(\frac{\alpha_{1}}{d^{k+1/2*}} \frac{\alpha_{1}}{s^{k+1/2*}} u^{k+1/2*} \right) - \frac{\Delta t \delta_{\alpha_{1}}}{2\Delta\alpha_{1}^{2}(\mu_{1})_{m}} \left[\frac{\alpha_{1}}{d^{k+1/2*}} K_{\alpha_{1}}^{k+1/2*} \frac{\delta_{\alpha_{1}}(s^{k+1/2*})}{\alpha_{1}(\mu_{1})_{m}} \right] + \frac{\Delta t}{2(\mu_{2})_{n}\Delta\alpha_{2}} \delta_{\alpha_{2}} \left(\frac{\alpha_{2}}{d^{k}} \frac{\alpha_{2}}{s^{k}} v^{k} \right)$$

$$(24)$$

$$-\frac{\Delta t \delta_{\alpha_2}}{2\Delta \alpha_2^2} \left[\frac{\alpha_1}{d^k} K_{\alpha_2}^k \frac{\delta_{\alpha_2}(s^k)}{(\mu_2)_p} \right] = 0 \quad \text{at } (n,m)$$

If we place all terms at time level k+1/2* on the left-hand side of the equation and expand $K_{\mathbf{x}} \equiv K_{\alpha}$

$$\frac{(ds)_{n,m}^{k+1/2^{*}} + \frac{\Delta t}{2\Delta\alpha_{1}(u_{1})_{m}} \left[\frac{\left(n_{n,m+1}^{k+1/2^{*}} - h_{n,m} + n_{n,m}^{k+1/2^{*}} - h_{n,m}\right)}{2} u_{n,m+1/2}^{k+1/2^{*}} \frac{\left(\frac{s_{n,m+1}^{k+1/2^{*}} + s_{n,m}^{k+1/2^{*}}}{n_{n,m+1/2}}\right)}{2} - \frac{\left(n_{n,m-1}^{k+1/2^{*}} - h_{n,m} + n_{n,m}^{k+1/2^{*}} - h_{n,m}\right)}{2} u_{n,m-1/2}^{k+1/2^{*}} \frac{\left(\frac{s_{n,m+1}^{k+1/2^{*}} + s_{n,m}^{k+1/2^{*}}}{n_{n,m}}\right)}{2} - \frac{\Delta t}{2\Delta\alpha_{1}^{2}(u_{1})_{m}} \left[\frac{\left(n_{n,m+1}^{k+1/2^{*}} - h_{n,m+1} + n_{n,m}^{k+1/2^{*}} - h_{n,m}\right)}{n_{n,m}} \frac{\left(\frac{s_{n,m+1}^{k+1/2^{*}} - s_{n,m}^{k+1/2^{*}}}{n_{n,m+1/2}}\right)}{(u_{1})_{m+1/2}} \frac{s_{n,m+1/2}^{k+1/2^{*}}}{s_{n,m+1/2}} - \frac{\left(n_{n,m+1}^{k+1/2^{*}} - h_{n,m}\right)}{n_{n,m+1/2}} \frac{\left(\frac{s_{n,m+1}^{k+1/2^{*}} - s_{n,m}^{k+1/2^{*}}}{n_{n,m+1/2}}\right)}{n_{n,m+1/2}} \left(\frac{s_{n,m}^{k+1/2^{*}} - s_{n,m-1}^{k+1/2^{*}}}{n_{n,m+1/2}}\right)}{n_{n,m+1/2}}$$

Collecting all terms in Equation 23 at time level $\,k\,\,$ denoting the result as B_m , we obtain $\,K_y \, \stackrel{\Xi}{=} \, K_{\alpha_2}^{}$

$$B_{m} = (ds)_{n,m}^{k} - \frac{\Delta t}{2\Delta\alpha_{2}(\mu_{2})_{n}} \left[\frac{\left(n_{n+1,m}^{k} - h_{n+1,m} + n_{n,m}^{k} - h_{n,m} \right)}{2} v_{n+1/2,m}^{k} \frac{\left(s_{n+1,m}^{k} + s_{n,m}^{k} \right)}{2} \right] \\ - \frac{\left(n_{n-1,m}^{k} - h_{n-1,m} + n_{n,m}^{k} - h_{n,m} \right)}{2} v_{n-1/2,m}^{k} \frac{\left(s_{n-1,m}^{k} + s_{n,m}^{k} \right)}{2} \right] \\ + \frac{\Delta t}{2(\mu_{2})_{n}(\Delta\alpha_{2})^{2}} \left[\frac{\left(n_{n+1,m}^{k} - h_{n,m} + n_{n,m}^{k} - h_{n,m} \right) \left(s_{n+1,m}^{k} - s_{n,m}^{k} \right)}{2} v_{n+1/2,m}^{k} \right] \\ - \frac{\left(n_{n-1,m}^{k} + h_{n-1,m} + n_{n,m}^{k} - h_{n,m} \right) \left(s_{n,m}^{k} - s_{n-1,m}^{k} \right)}{2} v_{n-1/2,m}^{k}}{2} v_{n-1/2,m}^{k}$$

In Equation 25 we define $-a_{n,m-1}$, $a_{n,m+1}$, and $a_{n,m}$ as follows

$$-a_{n,m-1} = \frac{\Delta t \left(\frac{\alpha_1}{d}\right)_{k+1/2}^{k+1/2}}{2\Delta \alpha_1 (\mu_1)_m} \left[\frac{u_{n,m-1/2}^{k+1/2}}{2} + \frac{(K_x)_{n,m-1/2}^{k+1/2}}{\Delta \alpha_1 (\mu_1)_{m-1/2}} \right]$$
(27)

$$a_{n,m+1} = \frac{\Delta t \left(\frac{\alpha_1}{d}\right)_{n,m+1/2}^{k+1/2*}}{2\Delta \alpha_1 (\mu_1)_m} \left[\frac{u_{n,m+1/2}^{k+1/2*}}{2} - \frac{(K_x)_{n,m+1/2}^{k+1/2*}}{\Delta \alpha_1 (\mu_1)_{m+1/2}} \right]$$
(28)

$$a_{n,m} = d_{n,m}^{k+1/2*} + \frac{\Delta t}{2\Delta\alpha_1(\mu_1)_m} \left[\frac{\left(\frac{\alpha_1}{du}\right)_{n,m+1/2}}{2} - \frac{\left(\frac{\alpha_1}{du}\right)_{n,m-1/2}}{2} \right]$$

$$+ \frac{\Delta t}{2\Delta \alpha_{1}^{2}(\mu_{1})_{m}} \left[\frac{\left(\frac{\alpha_{1}}{dK}\right)_{k+1/2}^{k+1/2}}{(\mu_{1})_{m+1/2}} + \frac{\left(\frac{\alpha_{1}}{dK}\right)_{k+1/2}^{k+1/2}}{(\mu_{1})_{m-1/2}} \right]$$
(29)

19. Collecting all results we obtain the following interior equation for the X-Sweep

$$a_{n,m-1} s_{n,m-1}^{k+1/2*} + a_{n,m} s_{n,m}^{k+1/2*} + a_{n,m+1} s_{n,m+1}^{k+1/2*} = B_{m}$$
 (30)

20. The approximations for the Y-Sweep may now be written as follows:

$$\delta_{t}^{k+1/2*}(ds) + \frac{\Delta t \delta_{\alpha_{2}}}{2\Delta \alpha_{2}(\mu_{2})_{n}} \left(\frac{\alpha_{2}}{d^{k+1}} \frac{\alpha_{2}}{s^{k+1}} v^{k+1} \right) - \frac{\Delta t \delta_{\alpha_{2}}}{2\Delta \alpha_{2}^{2}(\mu_{2})_{n}} \left[\frac{\alpha_{2}}{d^{k+1}} \kappa_{\alpha_{2}}^{k+1} \frac{\delta_{\alpha_{2}}(s^{k+1})}{(\mu_{2})_{n}} \right]$$

$$+ \frac{\Delta t \delta_{\alpha_{1}}}{2\Delta \alpha_{1}(\mu_{1})_{m}} \left(\frac{\alpha_{1}}{d^{k+1/2*}} \frac{\alpha_{1}}{s^{k+1/2*}} \frac{\alpha_{1}}{u^{k+1/2*}} v^{k+1/2*} \right) + \frac{\Delta t \delta_{\alpha_{1}}}{2\Delta \alpha_{1}^{2}(\mu_{1})_{m}} \left[\frac{\alpha_{1}}{d^{k+1/2*}} \kappa_{\alpha_{1}}^{k+1/2*} \frac{\delta_{\alpha_{1}}(s^{k+1/2*})}{(\mu_{1})_{m}} \right] = 0 \quad \text{at} \quad (n,m)$$

$$(31)$$

Expanding Equation 31 by employing Equation 22 and collecting terms at time level k+1 on the left-hand side and leaving terms at time level k+1/2* on the right-hand side, the following interior equation for the Y-Sweep is obtained:

$$a_{n-1,m} s_{n-1,m}^{k+1} + a_{n,m} s_{n,m}^{k+1} + a_{n+1,m} s_{n+1,m}^{k+1} = B_n$$
 (32)

where $\left(K_{x} \equiv K_{\alpha_{1}}, K_{y} \equiv K_{\alpha_{2}}\right)$

$$-a_{n-1,m} = \frac{\Delta t \left(\frac{\alpha_2}{d}\right)_{n-1/2,m}^{k+1}}{2\Delta \alpha_2(\mu_2)_n} \left[\frac{v_{n-1/2,m}^{k+1}}{2} + \frac{(K_y)_{n-1/2,m}^{k+1}}{\Delta \alpha_2(\mu_2)_{n-1/2}} \right]$$
(33)

$$a_{n+1,m} = \frac{\Delta t^{\left(\frac{\alpha_{2}}{d}\right)}_{n+1/2,m}^{k+1}}{2^{\Delta\alpha_{2}(\mu_{2})}_{n}} \left[\frac{v_{n+1/2,m}^{k+1}}{2} - \frac{(K_{y})_{n+1/2,m}^{k+1}}{\Delta\alpha_{2}(\mu_{2})_{n+1/2}} \right]$$
(34)

$$a_{n,m} = d_{n,m}^{k+1} + \frac{\Delta t}{2\Delta \alpha_2(\mu_2)_n} \left[\frac{\left(\frac{\alpha_2}{dv}\right)_{k+1}}{2} - \frac{\left(\frac{\alpha_2}{dv}\right)_{k+1}_{n-1/2,m}}{2} \right]$$

$$+\frac{\Delta t}{2\Delta \alpha_{2}^{2}(\mu_{2})_{n}}\left[\frac{\left(\frac{\alpha_{2}}{dK_{y}}\right)_{n+1/2,m}^{k+1}}{(\mu_{2})_{n+1/2}}+\frac{\left(\frac{\alpha_{2}}{dK_{y}}\right)_{n-1/2,m}^{k+1}}{(\mu_{2})_{n-1/2}}\right]$$
(35)

$$B_{n} = (ds)_{n,m}^{k+1/2*} - \frac{\Delta t}{2(\mu_{1})_{m}\Delta\alpha_{1}} \left[\left(\frac{\alpha_{1}}{d} \frac{\alpha_{1}}{s} \right)_{n,m+1/2}^{k+1/2*} u_{n,m+1/2}^{k+1/2*} - \left(\frac{\alpha_{1}}{d} \frac{\alpha_{1}}{s} \right)_{n,m-1/2}^{k+1/2*} u_{n,m-1/2}^{k+1/2*} \right] + \frac{\Delta t}{2(\mu_{1})_{m}(\Delta\alpha_{1})^{2}} \left[\left(\frac{\alpha_{1}}{dK}_{x} \right)_{n,m+1/2}^{k+1/2*} \frac{\left(s_{n,m+1}^{k+1/2*} - s_{n,m}^{k+1/2*} \right)}{(\mu_{1})_{m+1/2}} - \left(\frac{\alpha_{1}}{dK}_{x} \right)_{n,m-1/2}^{k+1/2*} \frac{\left(s_{n,m}^{k+1/2*} - s_{n,m-1}^{k+1/2*} \right)}{(\mu_{1})_{m-1/2}} \right]$$
(36)

21. <u>Leendertse FTUS multioperational scheme</u>. The following finite difference equation is considered as an approximation to the nonlinear transport equation (21):

$$\delta'_{t}^{k}(ds) + \frac{\Delta t}{2\Delta \alpha_{1}(\mu_{1})_{m}} \delta_{\alpha_{1}} \left(\frac{\alpha_{1}}{d}^{k+1} \frac{u}{s}^{k+1} + \frac{\alpha_{1}}{d}^{k} \frac{u}{s}^{k}_{1} u^{k}\right)$$

$$+ \frac{\Delta t}{2\Delta \alpha_2(\mu_2)_n} \delta_{\alpha_2} \left(\frac{\alpha_2}{d} k + 1 \frac{v}{s_2} v^{k+1} + \frac{\alpha_2}{d} k \frac{v}{s_2} v^k \right)$$

$$-\frac{\Delta t}{2(\Delta \alpha_{1})^{2}(\mu_{1})_{m}} \delta_{\alpha_{1}} \left[\frac{\alpha_{1}}{d^{k+1}} K_{\alpha_{1}}^{k+1} \frac{\delta_{\alpha_{1}}(s^{k+1})}{(\mu_{1})_{m}} + \frac{\alpha_{1}}{d^{k}} K_{\alpha_{1}}^{k} \frac{\delta_{\alpha_{1}}(s^{k})}{(\mu_{1})_{m}} \right]$$

$$-\frac{\Delta t}{2(\Delta \alpha_2)^2(\mu_2)_n} \delta_{\alpha_2} \left[\frac{\alpha_2}{d^{k+1}} K_{\alpha_2}^{k+1} \frac{\delta_{\alpha_2}(s^{k+1})}{(\mu_2)_n} + \frac{\alpha_2}{d^k} K_{\alpha_2}^k \frac{\delta_{\alpha_2}(s^k)}{(\mu_2)_n} \right] = 0 \quad \text{at (n,m)}$$

22. The following upwind difference operators are used in the above equation and are defined at (n,m) as follows:

$$\frac{f^{k}}{s_{1}} = \begin{cases}
s^{k}_{n,m-1/2} & f^{k}_{n,m} \ge 0 \\
s^{k}_{n,m+1/2} & f^{k}_{n,m} < 0
\end{cases}$$

$$\frac{f^{k}}{s_{2}} = \begin{cases}
s^{k}_{n-1/2,m} & f^{k}_{n,m} \ge 0 \\
s^{k}_{n+1/2,m} & f^{k}_{n,m} < 0
\end{cases}$$
(38)

(37)

- 23. To effect the solution of this scheme, the inversion of an unbanded matrix is again required. Thus, an ADI scheme similar to the previous technique (upwind differencing is employed for the advective terms) is used. The necessary modifications for the X-Sweep are shown in Table 1 while those employed for the Y-Sweep are given in Table 2.
- 24. <u>Flux correction procedures.</u> If the factorization terms are ignored, the schemes above may be written in the following flux format:

$$d_{n,m}^{k+1} s_{n,m}^{I} = d_{n,m}^{k} s_{n,m}^{k} - \left[\Delta \alpha_{1} (\mu_{1})_{m} \Delta \alpha_{2} (\mu_{2})_{n} \right]^{-1} \left(F_{n+1/2,m}^{I} - F_{n+1/2,m}^{I} \right)$$

$$- F_{n-1/2,m}^{I} + F_{n,m+1/2}^{I} - F_{n,m-1/2}^{I} \right)$$
(39)

where
$$t = k\Delta t$$
, $x = \sum_{i} (\mu_{1})_{i} \Delta \alpha_{1}$, $y = \sum_{i} (\mu_{2})_{i} \Delta \alpha_{2}$

 $S_{n,m}^k \equiv \text{concentration at location } (n,m) \text{ at time level } k$ $\Delta \alpha_1(\mu_1)_m \equiv x \text{ space step at } m$

 $\Delta \alpha_2(\mu_2)_n \equiv y$ space step at n

I ≡ general index at time level k+1 , which we set to H or L for the higher or lower scheme, respectively

 $F_{n\pm1/2,m\pm1/2}^{I}$ = fluxes through the appropriate cell faces of cell (n,m). Form is dependent upon the finite difference formulation

We observe from Equation 39 that the difference between the higher and lower order scheme at (n,m) may be written as follows:

$$\left(\mathbf{s}_{n,m}^{H} - \mathbf{s}_{n,m}^{L} \right) = - \left[\Delta \alpha_{1}(\mu_{1})_{m} \Delta \alpha_{2}(\mu_{2})_{n} \mathbf{d}_{n,m}^{k+1} \right]^{-1} \left[\left(\mathbf{F}_{n+1/2,m}^{H} - \mathbf{F}_{n+1/2,m}^{L} \right) - \left(\mathbf{F}_{n-1/2,m}^{H} - \mathbf{F}_{n-1/2,m}^{L} \right) + \left(\mathbf{F}_{n,m+1/2}^{H} - \mathbf{F}_{n,m+1/2}^{L} \right) - \left(\mathbf{F}_{n,m-1/2}^{H} - \mathbf{F}_{n,m-1/2}^{L} \right) \right]$$

$$(40)$$

Note this difference may be expressed as an array of fluxes between adjacent grid points and is the condition required to effect the flux correction procedures as given by Zalesak (1979). We next develop the flux expressions for the higher (F^L) and lower (F^L) order schemes. In order to aid in notation, we make the following definition for an arbitrary variable, F:

Table 1
X-Sweep Modifications FTUS

Equation	FTCS	FTUS
26	$\frac{\left(s_{n+1,m}^{k}+s_{n,m}^{k}\right)}{2}$	$s_{n,m}^{k}$ $v_{n+1/2,m}^{k} \ge 0$ $s_{n+1,m}^{k}$ $v_{n+1/2,m}^{k} < 0$
26	$\frac{\left(s_{n-1,m}^k + s_{n,m}^k\right)}{2}$	$s_{n+1,m}^{k}$ $v_{n+1/2,m}^{k} \ge 0$ $s_{n,m}^{k}$ $v_{n-1/2,m}^{k} \le 0$
27	$\frac{u^{k+1/2*}}{u_{n,m-1/2}}$	max $\left(0, u_{n,m-1/2}^{k+1/2*}\right)$
28	$\frac{u^{k+1/2*}}{\frac{n,m+1/2}{2}}$	min $\left(0, u_{n,m+1/2}^{k+1/2*}\right)$
29	$\frac{\left(\frac{\alpha_1}{\mathrm{du}}\right)_{k+1/2}}{\frac{n,m+1/2}{2}}$	$\max \left[0, \left(\frac{\alpha_1}{du} \right)_{n, m+1/2}^{k+1/2*} \right]$
29	$\frac{\binom{\alpha_1}{du}_{n, m-1/2}^{k+1/2*}}{\frac{2}}$	min $\left[0, \left(\frac{\alpha_1}{du}\right)_{n,m-1/2}^{k+1/2}\right]$

Table 2
Y-Sweep Modifications FTUS

Equation	FTCS	FTUS
33	$\frac{\mathbf{v}_{\mathbf{n-1/2,m}}^{\mathbf{k+1}}}{2}$	$\max \left(0, v_{n-1/2,m}^{k+1}\right)$
34	$\frac{\mathbf{v}_{n+1/2,m}^{k+1}}{2}$	min $\left(0, v_{n+1/2,m}^{k+1}\right)$
35	$\frac{\binom{\alpha_2}{dv}_{n+1/2,m}}{2}$	$\max \left[0, \left(\frac{\alpha_2}{dv} \right)_{n+1/2, m}^{k+1} \right]$
35	$\frac{\left(\frac{\alpha_2}{dv}\right)_{k+1}}{n-1/2,m}$	$\min \left[0, \left(\frac{\alpha_2}{dv}\right)_{n-1/2, m}^{k+1}\right]$
36	$\left(\frac{\alpha_1}{d} \frac{\alpha_1}{s}\right)_{n,m+1/2}^{k+1/2*}$	$\frac{a_1}{d^{k+1/2*}} + \frac{1}{d^{k+1/2*}} + \frac{1}{d^{k+1/2*}} = 0$ $u_{n,m+1/2}^{k+1/2*} \ge 0$
		$\frac{\alpha_1}{d_{n,m+1/2}} k+1/2 * s_{n,m+1}^{k+1/2} * s_{n,m+1}^{k+1/2} * u_{n,m+1/2}^{k+1/2} < 0$
36	$\left(\frac{\alpha_1}{d} \frac{\alpha_1}{s}\right)_{n,m-1/2}^{k+1/2*}$	$\frac{a_1}{d_{n,m-1/2}^{k+1/2}} s_{n,m-1}^{k+1/2} \qquad u_{n,m-1/2}^{k+1/2} \ge 0$
		$\frac{a_1}{d_{n,m-1/2}}^{k+1/2*} s_{n,m}^{k+1/2*} \qquad u_{n,m-1/2}^{k+1/2*} < 0$

$$F_{n,m}^{k+1/2} = \left(F_{n,m}^{k+1} + F_{n,m}^{k}\right) / 2$$
 (41)

- 25. For the higher order scheme we employ the FTCS scheme written in Equation 23 in which the factorization terms developed in the multioperational method are not shown. Equation 23 may be written in the form of Equation 39, where the total fluxes are presented as the sum of advective and diffusive fluxes.
 - 26. From Equation 23 one then obtains for the advective fluxes:

$$F_{\underline{n+1/2},m}^{H_{A}} = v_{\underline{n+1/2},m}^{k+1/2} \Delta t(\mu_{1})_{\underline{m}} \Delta \alpha_{1} \left[\left(\frac{\underline{s^{H} + \underline{s^{k}}}}{2} \right)_{\underline{n+1},m} d_{\underline{n+1},m}^{k+1/2} + \left(\frac{\underline{s^{H} + \underline{s^{k}}}}{2} \right)_{\underline{n,m}} d_{\underline{n,m}}^{k+1/2} \right] / 2$$

$$+ \left(\frac{\underline{s^{H} + \underline{s^{k}}}}{2} \right)_{\underline{n,m}} d_{\underline{n,m}}^{k+1/2}$$
(42)

$$F_{n,m+1/2}^{HA} = u_{n,m+1/2}^{k+1/2} \Delta t (\mu_2)_n \Delta \alpha_2 \left[\left(\frac{s^H + s^k}{2} \right)_{n,m+1}^{k+1/2} d_{n,m+1}^{k+1/2} + \left(\frac{s^H + s^k}{2} \right)_{n,m}^{k+1/2} d_{n,m}^{k+1/2} \right] / 2$$
(43)

The diffusive fluxes are then given by the following relations $(K_x \equiv K_{\alpha_1}, K_y \equiv K_{\alpha_1})$:

$$F_{\underline{n+1/2},m}^{H_0} = \pm K y_{\underline{n+1/2},m}^{k+1/2} \frac{\Delta t (\mu_1)_m \Delta \alpha_1}{2} \times \frac{\left[(S^H + S^k)_{n,m} - (S^H + S^k)_{\underline{n+1},m} \right]}{\Delta \alpha_2 (\mu_2)_{n+1/2}} \frac{\left(d_{\underline{n+1},m}^{k+1/2} + d_{\underline{n,m}}^{k+1/2} \right)}{2}$$
(44)

$$F_{n,\underline{m+1/2}}^{H_0} = \pm K_{x_{n,\underline{m+1/2}}}^{k+1/2} \frac{\Delta t (\mu_2)_n \Delta \alpha_2}{2} \times \frac{\left[(S^H + S^k)_{n,\underline{m}} - (S^H + S^k)_{n,\underline{m+1}} \right] \left(\frac{d^{k+1/2} + d^{k+1/2}}{n,\underline{m+1}} \right)}{\Delta \alpha_1 (\mu_1)_{\underline{m+1/2}}} \frac{\Delta \alpha_1 (\mu_1)_{\underline{m+1/2}}}{2}$$
(45)

- 27. For the lower order scheme, the FTUS scheme written in Equation 37 is employed. Factorization terms generated by the multioperational method are not considered. Equation 37 is written in the form of Equation 39. The total fluxes are presented as the sum of advective and diffusive fluxes.
 - 28. From Equation 37 one obtains the following set of advective fluxes:

$$\mathbf{F}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{L}_{\mathbf{A}}} = \begin{cases} \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{k}+1/2} \geq 0 & \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{k}+1/2} \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{\Delta}\mathbf{t}}(\mathbf{u}_{1})_{\mathbf{m}}^{\mathbf{\Delta}\alpha_{1}} \left(\frac{\mathbf{S}^{\mathbf{L}} + \mathbf{S}^{\mathbf{k}}}{2}\right)_{\mathbf{n},\mathbf{m}}^{\mathbf{d}} \mathbf{v}_{\mathbf{n},\mathbf{m}}^{\mathbf{k}+1/2} \\ \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{k}+1/2} < 0 & \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{k}+1/2} \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{\Delta}\mathbf{t}}(\mathbf{u}_{1})_{\mathbf{m}}^{\mathbf{\Delta}\alpha_{1}} \left(\frac{\mathbf{S}^{\mathbf{L}} + \mathbf{S}^{\mathbf{k}}}{2}\right)_{\mathbf{n}+1,\mathbf{m}}^{\mathbf{d}\mathbf{k}+1/2} \\ \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{k}+1/2} < 0 & \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{k}+1/2} \mathbf{v}_{\mathbf{n}+1/2,\mathbf{m}}^{\mathbf{\Delta}\mathbf{t}}(\mathbf{u}_{1})_{\mathbf{m}}^{\mathbf{\Delta}\alpha_{1}} \left(\frac{\mathbf{S}^{\mathbf{L}} + \mathbf{S}^{\mathbf{k}}}{2}\right)_{\mathbf{n}+1,\mathbf{m}}^{\mathbf{d}\mathbf{k}+1/2} \end{cases}$$

$$(46)$$

$$F_{n-1/2,m}^{L} = \begin{cases} v_{n-1/2,m}^{k+1/2} \ge 0 & v_{n-1/2,m}^{k+1/2} \triangle t(u_1)_{m} \triangle \alpha_1 \left(\frac{s^L + s^k}{2}\right)_{n-1,m} d_{n-1,m}^{k+1/2} \\ v_{n-1/2,m}^{k+1/2} < 0 & v_{n-1/2,m}^{k+1/2} \triangle t(u_1)_{m} \triangle \alpha_1 \left(\frac{s^L + s^k}{2}\right)_{n,m} d_{n,m}^{k+1/2} \end{cases}$$

$$(47)$$

$$F_{n,m+1/2}^{L} = \begin{cases} u_{n,m+1/2}^{k+1/2} \ge 0 & u_{n,m+1/2}^{k+1/2} \Delta t(\mu_{2})_{n} \Delta \alpha_{2} \left(\frac{s^{L} + s^{k}}{2}\right)_{n,m} d_{n,m}^{k+1/2} \\ u_{n,m+1/2}^{k+1/2} < 0 & u_{n,m+1/2}^{k+1/2} \Delta t(\mu_{2})_{n} \Delta \alpha_{2} \left(\frac{s^{L} + s^{k}}{2}\right)_{n,m+1} d_{n,m+1}^{k+1/2} \end{cases}$$

$$(48)$$

$$F_{n,m-1/2}^{L} = \begin{cases} u_{n,m-1/2}^{k+1/2} \ge 0 & u_{n,m-1/2}^{k+1/2} \Delta t (\mu_2)_n \Delta \alpha_2 \left(\frac{s^L + s^k}{2} \right)_{n,m-1}^{d_{n,m-1}} d_{n,m-1}^{k+1/2} \\ u_{n,m-1/2}^{k+1/2} < 0 & u_{n,m-1/2}^{k+1/2} \Delta t (u_2)_n \Delta \alpha_2 \left(\frac{s^L + s^k}{2} \right)_{n,m}^{d_{n,m}} d_{n,m}^{k+1/2} \end{cases}$$

$$(49)$$

The diffusive fluxes are obtained from Equations 44 and 45 with $\,\,$ H $\,$ replaced by $\,$ L $\,$.

29. The antidiffusive fluxes are then computed as follows:

$$A_{n\pm 1/2,m} = F_{n\pm 1/2,m}^{HA} - F_{n\pm 1/2,m}^{LA} + F_{n\pm 1/2,m}^{HO} - F_{n\pm 1/2,m}^{LO}$$
 (50)

$$A_{n,m\pm 1/2} = F_{n,m\pm 1/2}^{HA} - F_{n,m\pm 1/2}^{LA} + F_{n,m\pm 1/2}^{HO} - F_{n,m\pm 1/2}^{LO}$$
 (51)

In computing the difference between the diffusive fluxes (third and fourth terms in the above expressions), note that the terms with $S_{n,m}^k$ may be completely eliminated.

30. Next the maximum and minimum cell values are determined:

$$S_{n,m}^{a} = \max(S_{n,m}^{k}, S_{n,m}^{L})$$
 $S_{n,m}^{b} = \min(S_{n,m}^{k}, S_{n,m}^{L})$ (52)

$$S_{n,m}^{\text{max}} = \max \left(S_{n-1,m}^{a}, S_{n,m}^{a}, S_{n+1,m}^{a}, S_{n,m-1}^{a}, S_{n,m+1}^{a} \right)$$
 (53)

$$S_{n,m}^{\min} = \min \left(S_{n-1,m}^{b}, S_{n,m}^{b}, S_{n+1,m}^{b}, S_{n,m-1}^{b}, S_{n,m+1}^{b} \right)$$
 (54)

31. Next the sum of all antidiffusive fluxes into cell (n,m), $P_{n,m}^{\mathsf{T}}$, is determined:

$$P_{n,m}^+ = \max(0, A_{n-1/2,m}) - \min(0, A_{n+1/2,m})$$

+
$$\max(0, A_{n,m-1/2})$$
 - $\min(0, A_{n,m+1/2})$ (55)

The maximum allowable mass into the cell, $Q_{n,m}^{\dagger}$, is then computed as follows:

$$Q_{n,m}^{+} = \left(S_{n,m}^{\text{max}} - S_{n,m}^{L}\right) \left[(\mu_{1})_{m} \Delta \alpha_{1} (\mu_{2})_{n} \Delta \alpha_{2} d_{n,m}^{k+1} \right]$$
(56)

32. Similarly, the sum of all antidiffusive fluxes out of cell (n,m), $P_{n,m}^{-}$, is determined:

$$P_{n,m}^- = \max(0, A_{n+1/2,m}) - \min(0, A_{n-1/2,m})$$

+
$$\max(0, A_{n,m+1/2})$$
 - $\min(0, A_{n,m-1/2})$ (57)

The maximum allowable mass to leave the cell, $Q_{n,m}$, is then computed:

$$Q_{n,m}^{-} = \left(S_{n,m}^{L} - S_{n,m}^{\min}\right) \left[(\mu_{1})_{m} \Delta \alpha_{1} (\mu_{2})_{n} \Delta \alpha_{2} d_{n,m}^{k+1} \right]$$
 (58)

33. The following ratios are next computed for use in determining the limiting coefficients:

$$R_{n,m}^{+} = \begin{cases} \min \left(1, Q_{n,m}^{+} / P_{n,m}^{+} \right) & P_{n,m}^{+} > 0 \\ 0 & P_{n,m}^{+} = 0 \end{cases}$$
 (59)

$$R_{n,m}^{-} = \begin{cases} \min \left(1, Q_{n,m}^{-} / P_{n,m}^{-} \right) & P_{n,m}^{-} > 0 \\ 0 & P_{n,m}^{-} = 0 \end{cases}$$
(60)

The limiting coefficients are then given by

$$C_{n+1/2,m} = \begin{cases} \min \left(R_{n+1,m}^{+}, R_{n,m}^{-} \right) & A_{n+1/2,m} \ge 0 \\ \min \left(R_{n,m}^{+}, R_{n+1,m}^{-} \right) & A_{n+1/2,m} < 0 \end{cases}$$

$$C_{n,m+1/2} = \begin{cases} \min \left(R_{n,m+1}^{+}, R_{n,m}^{-} \right) & A_{n,m+1/2} \ge 0 \\ \min \left(R_{n,m}^{+}, R_{n,m+1}^{-} \right) & A_{n,m+1/2} < 0 \end{cases}$$

$$(61)$$

34. The antidiffusive fluxes in Equations 50 and 51 are limited by multiplying by the limiting coefficients and the solution is advanced to the next time level:

$$s_{n,m}^{k+1} = s_{n,m}^{L} - \left[\Delta \alpha_{1}(\mu_{1})_{m} \Delta \alpha_{2}(\mu_{2})_{n} d_{n,m}^{k+1} \right]^{-1} c_{n+1/2,m}^{A} c_{n+1/2,m}^{A}$$

We observe that for $C_{n+1/2,m} = C_{n,m\pm 1/2} = 0$, $S_{n,m}^{k+1} = S_{n,m}^{L}$ and for $C_{n\pm 1/2,m} = C_{n,m\pm 1/2} = 1.0$, $S_{n,m}^{k+1} = S_{n,m}^{H}$.

35. The coding of the flux corrected transport procedures is presented in Subroutine CONC in Appendix A.

Three time level explicit scheme

- 36. In order to avoid the averaging of hydrodynamic quantities, which is performed when employing a two time level transport scheme with a three time level velocity scheme, a three time level explicit scheme is considered.
- 37. It is instructive to observe the form of the continuity equation employed in the multioperational hydrodynamic scheme.

X-Sweep:

$$\frac{1}{2\Delta t} \left(\eta^{\frac{1}{k}} - \eta^{k-1} \right)_{n,m} + \frac{1}{2(\mu_1) \frac{\Delta \alpha_1}{m}} \left[\left(u^{k+1} + u^{k-1} \right) \frac{\alpha_1}{d^k} \right|_{n,m+1/2} - \left(u^{k+1} + u^{k-1} \right) \frac{\alpha_1}{d^k} \right|_{n,m-1/2} \\
+ \frac{1}{(\mu_2) \frac{\Delta \alpha_2}{n}} \left[v^{k-1} \frac{\alpha_2}{d^k} \right|_{n+1/2,m} - v^{k-1} \frac{\alpha_2}{d^k} \right|_{n-1/2,m} = 0 \quad \text{at } (n,m) \tag{63}$$

with

$$\frac{\alpha_1}{d_{n,m\pm 1/2}} = d_{n,m\pm 1}^k + d_{n,m}^k$$

$$\frac{\alpha_2}{d_{n\pm 1/2,m}} = d_{n\pm 1,m}^k + d_{n,m}^k$$

and

$$d_{n,m}^{k} = \eta_{n,m}^{k} - h_{n,m}$$

Y-Sweep:

$$\frac{1}{2\Delta t} \left(\eta_{n,m}^{k+1} - \eta_{n,m}^{*} \right) + \frac{1}{2(\mu_{2})_{n}^{\Delta \alpha_{2}}} \left[(v^{k+1} - v^{k-1})^{\frac{\alpha_{2}}{d}k} \bigg|_{n+1/2,m} - (v^{k+1} - v^{k-1})^{\frac{\alpha_{2}}{d}k} \bigg|_{n-1/2,m} \right] = 0$$

$$at (n,m)$$

where

 $\Delta t \equiv time step length$

 $\eta^* \equiv \text{water surface elevation at intermediate time level} * k±1$

 $\eta_{n,m}^{k\pm 1}$ = water surface elevation at time level k±1 at cell (n,m)

 $\Delta \alpha_1 \equiv \alpha_1$ space increment

 $\Delta \alpha_2 \equiv \alpha_2$ space increment

$$u_{n,m+1/2}^{k+1} \equiv x - \alpha_1$$
 velocity component at time level k+1 at cell (n,m)

$$u_{n,m+1/2}^{k-1} \equiv x - \alpha_1$$
 velocity component at time level k-1 at cell (n,m)

$$v_{n+1/2,m}^{k+1} \equiv y - \alpha_2$$
 velocity component at time level k+1 at cell (n,m)

$$v_{n+1/2,m}^{k-1} \equiv y - \alpha_2$$
 velocity component at time level k-1 at cell (n,m) $d_{n,m}^k \equiv \text{water depth at time level } k$ at cell (n,m)

If we eliminate the intermediate level η^* ; e.g., solve for η^* in Equation 63 and substitute in Equation 64, we obtain:

$$\frac{\left(\eta_{n,m}^{k+1} - \eta_{n,m}^{k-1}\right)}{2\Delta t} + \frac{1}{2\left(\mu_{1}\right)_{m}^{\Delta\alpha_{1}}} \left[\left(u^{k+1} + u^{k-1}\right)^{-\frac{\alpha_{1}}{d}k} \right|_{n,m+1/2} - \left(u^{k+1} + u^{k-1}\right)^{-\frac{\alpha_{1}}{d}k} \right|_{n,m-1/2} + \frac{1}{2\left(\mu_{2}\right)_{n}^{\Delta\alpha_{2}}} \left[\left(v^{k+1} + v^{k-1}\right)^{-\frac{\alpha_{2}}{d}k} \right|_{n+1/2,m} - \left(v^{k+1} + v^{k-1}\right)^{-\frac{\alpha_{2}}{d}k} \right|_{n-1/2,m} = 0$$
(65)

Since $d_{n,m}^k = \eta_{n,m}^k - h_{n,m}$, Equation 65 is a full three time level scheme. In order to develop a three time level volume consistent transport scheme, we associate in the advective terms $d_{n,m}^k S_{n,m}^k \equiv d_{n,m}^k$; e.g.,

$$\frac{\left(d_{n,m}^{k+1}S_{n,m}^{k+1} - d_{n,m}^{k-1}S_{n,m}^{k-1}\right)}{2\Delta t} + \frac{1}{2(\mu_{1})_{m}^{\Delta \alpha_{1}}} \left[(u^{k+1} + u^{k-1}) \frac{\alpha_{1}}{d}^{k} \frac{\alpha_{1}}{s}^{k} \right|_{n,m+1/2} - (u^{k+1} + u^{k-1}) \frac{\alpha_{1}}{d}^{k} \frac{\alpha_{1}}{s}^{k} \right]_{n,m-1/2} \\
+ \frac{1}{2(\mu_{2})_{n}^{\Delta \alpha_{2}}} \left[(v^{k+1} + v^{k-1}) \frac{\alpha_{2}}{d}^{k} \frac{\alpha_{2}}{s}^{k} \right|_{n+1/2,m} - (v^{k+1} + v^{k-1}) \frac{\alpha_{2}}{d}^{k} \frac{\alpha_{2}}{s}^{k} \right]_{n-1/2,m} \\
= + \frac{1}{(\mu_{1})_{m}^{(\Delta \alpha_{1})^{2}}} \left[\frac{\alpha_{1}}{d}^{k-1} \kappa_{1}^{k-1}}{a_{1}} \right|_{n,m+1/2} \frac{\left(s_{n,m+1}^{k-1} - s_{n,m}^{k-1}\right)}{(\mu_{1})_{m+1/2}} - \frac{\alpha_{1}}{d}^{k-1} \kappa_{1}^{k-1}}{a_{1}^{k-1}} \right|_{n,m-1/2} \frac{\left(s_{n,m-1}^{k-1} - s_{n,m-1}^{k-1}\right)}{(\mu_{1})_{m-1/2}} \\
+ \frac{1}{(\mu_{2})_{n}^{(\Delta \alpha_{2})^{2}}} \left[\frac{\alpha_{2}}{d}^{k-1} \kappa_{1}^{k-1}}{a_{2}^{k-1}} \right|_{n+1/2,m} \frac{\left(s_{n+1,m}^{k-1} - s_{n,m}^{k-1}\right)}{(\mu_{2})_{n+1/2}} - \frac{\alpha_{2}}{d}^{k-1} \kappa_{1}^{k-1}}{a_{2}^{k-1}} \right|_{n-1/2,m} \frac{\left(s_{n,m}^{k-1} - s_{n-1,m}^{k-1}\right)}{(\mu_{2})_{n-1/2}} \right]$$

38. The stability properties of the above scheme were investigated for the range of conditions to be simulated in Mississippi Sound. The scheme was stable over this range of flow conditions. Details may be found in Schmalz (1984). The coding of the three time level scheme is presented in Subroutine CONCE in Appendix A.

Dispersion coefficient formulation

- 39. To close the numerical approximations to the two-dimensional, depth-averaged transport equation, relations for the effective dispersion coefficients may be developed in terms of flow field properties.
- 40. The effective disperison coefficients are assumed to have the following form:

$$K_{x}^{*} = C_{x}\sqrt{g} \frac{|u|h}{C} + D_{x} ; \quad K_{y}^{*} = C_{y}\sqrt{g} \frac{|v|h}{C} + D_{y}$$
 (67)

where

 $K_x^*, K_y^* \equiv \text{effective dispersion coefficients in the } x- \text{ and } y- \text{directions,}$ respectively

g ≡ acceleration due to gravity

u,v ≅ velocity components in the x- and y-directions, respectively

h ≅ water depth

C ≅ Chezy coefficient

 $C_{y}, C_{y} \equiv$ dispersion factors in the x- and y-directions, respectively

 D_x, D_y \equiv dispersion offsets due to wind effects in the x- and y-directions, respectively $(D_x, D_y > 0)$

For a unidirectional flow in an infinitely wide channel in the x-direction , Elder (1959) found $C_x = 5.93$ and $C_y = 0.23$. Harleman et al. (1959) has converted Taylor's result (1954) for pipe flow and determined $C_x = 14.3\sqrt{2}$. In attempting to apply these results to a two-dimensional flow problem the following approach is employed. Initially, C_x , C_y , D_x , and D_y are specified by the user as model input. The cell face conditions for each cell are examined independently in each coordinate direction. For a no-flux cell face condition, C_x or C_y and D_x or D_y are set to zero. For a standard flow condition, the advective flag system is examined to determine if the flow is restricted in the x- or y-direction. If the flow is restricted, C_x or C_y is reduced by a user-specified factor.

PART III: MODEL INPUT REQUIREMENTS

- 41. The constituent transport schemes are included with the hydrodynamics as separate subroutines in WIFM-SAL. Therefore, the model user must also be concerned with both the hydrodynamic input requirements as well as those of the transport computations. The complete input requirements for WIFM-SAL are presented in Appendix B and consist of 29 separate card groups. Constituent transport input requirements consist of the following categories:
 - a. Constituent Simulation Control.
 - b. Boundary Condition Control.
 - c. Boundary Condition Data.
 - d. Wind Data.
 - e. Constituent Initial Condition Data.
 - f. Dispersion Coefficient Data.
 - g. Output Control.

Each category will be discussed in detail below with reference to the appropriate card groups contained in Appendix B.

Constituent Simulation Control

42. This data group is contained in Card Group 2a. The model user sets ISAL = 1 to consider constituent transport in conjunction with the hydrodynamics. The desired transport scheme is selected by specifying ISALS. For ISALS = 1, the FCT scheme is employed, while for ISALS = 2, the full three time level explicit scheme is used. Constituent transport computations are initiated ISALC time steps after the start of the hydrodynamic computations. The user may set ISALC \neq 0 in order to allow for the hydrodynamic computations to be free from initial condition effects before considering constituent transport. CMAX and XMS are self-explanatory.

Boundary Condition Control

43. This data group is contained in Card Groups 3a and 3b. In Card Group 3a the user specifies the number of tidal elevation signals specified by tidal constituents. For a simulation over a global grid, NGLOB = 0, and NTI is specified as the number of tidal boundary (water surface elevation and

constituent level) signals along the seaward boundary used for interpolation. For a simulation over a refined grid, NTI = 0, and NGLOB is specified as the number of previously saved tidal signals (water surface elevations and constituent levels) generated from a global grid simulation to be used for cell-centered interpolation along the boundary of the refined grid.

44. In Card Group 3b, the user specifies the grid indices for the grid employed in the current simulation where the known tidal signals are available.

Boundary Condition Data

- 45. Boundary condition format is specified in Card Group 3. The user specifies ITID as the number of entries in the tidal (elevation and constituents level) input and/or flow (discharge and constituent level) input data tables. The number of time steps between entries in these tables is common and is specified as JTID.
- 46. In Card Groups 20c and 21b, the constituent levels associated with tidal and flow inputs are specified, respectively.

Wind Data

- 47. Detailed requirements will not be discussed here. Let it suffice to say that wind conditions may want to be considered when simulating constituent transport. The pertinent input variables requiring specification are as follows:
 - a. WA, THETA in Card Group 4.
 - b. NTABLE in Card Group 5.
 - <u>c</u>. WAT_i, THAT_i in Card Group 6 (optional depending on wind format).

Constituent Initial Condition Data

48. In Card Group 13a, the user specifies a single format or combination of formats to be used for specifying the constituent initial condition. IDEPTH specifies the number of depth intervals used to interpolate based upon depth. If IDEPTH $\neq 0$, a set of initial constituent levels TMP $_N$ are associated with depth values $D_{N,1}$ as specified in Card Group 13b. IFIELD

specifies the number of patches in which initial levels will be specified on a cell-by-cell basis. If IFIELD $\neq 0$, the limits of patch and the individual cell constituent levels are specified in turn for each patch in Card Group 13c. IZONE specifies that a number of zones in which the initial constituent level will be a constant will be assumed. If IZONE $\neq 0$, the number of zones, the limits of the zone, and the constant value of initial constituent level for the zone are specified in Card Group 13d.

49. There is considerable flexibility in specifying initial constituent levels. Each format may be used individually or to override the previous format. For example, the user may specify the initial conditions using depth interpolation. In selected areas of the grid where detailed information is available, the patch concept can be used to override the depth interpolation. In still different areas of the grid, the zone concept can be used to specify a uniform level.

Dispersion Coefficient Data

- 50. Dispersion factors and offsets due to wind effects are specified in turn for each coordinate direction in a zone format as shown in Card Group 13e.
- 51. The reduction factor applied to the dispersion factors in cases of flow restriction is specified in Card Group 17b.

Output Control

- 52. Snapshots of the entire constituent field are printed after completion of up to 32 user-specified time steps during the simulation. Time step completion data are read in Card Group 7 in the NPRINT array.
- 53. Alternatively, the user may examine constituent level histories at NGAGE locations at NFREQ time step intervals as specified in Card Group 5. The NGAGE locations are specified in terms of the grid indicies in Card Group 8.

PART IV: APPLICATION TO MISSISSIPPI SOUND

54. Both the FCT and the three time level schemes have been applied to the study of salinity distributions in Mississippi Sound by Schmalz (1984). The schemes were exercised on a global grid and also over a local refined grid. Wind sensitivity results for both grid applications are presented in turn below.

Global Grid Results

- 55. The horizontal salinity distribution was simulated within Mississippi Sound and adjacent areas employing an exponentially stretched global grid as shown in Figure 3. This grid employs 115 × 59 = 6785 cells. Maximum spatial resolution (approximately 3500 ft*) is obtained in the passes into Mississippi Sound. Depths within Mississippi Sound are relatively shallow (10-20 ft), except in the navigation channels, which are normally maintained at 30 to 35 ft. As a result, the gravity wave speed within the Sound is less than 38 fps, resulting in an explicit time step limit of approximately 100 sec. All simulation employed a 360-sec (6 min) time step, resulting in a maximum spatial Courant number of less than 4 within the Sound.
- 56. Hydrodynamics and salinity conditions over the period 20-24 Sep 1980 were simulated. Water surface elevations along the seaward boundary were obtained from a Gulf Tide Model developed by Reid and Whitaker (1981). Salinity transect data were available on 20 and 21 September. These values were located on the global grid and two rectangular areas were set up in which salinity values were visually interpolated from the located transect values. National Marine Fisheries data were obtained for cruises No. 106 (Apr 1980) and No. 112 (Nov 1980) of the OREGON II. These data provided a general understanding of salinity patterns in the vicinity of the Mississippi Delta. A deep sea vertically averaged value of 36 ppt was employed.
- 57. Initial conditions were assigned in a three step process as shown in Table 3. In step one, values were assigned based on cell water depth. In step two, salinity values were specified within Mississippi Sound based on salinity transect data. In step three, initial salinity values within

^{*} A table of factors for converting U.S. customary units of measurement to metric (SI) is presented on page 3.

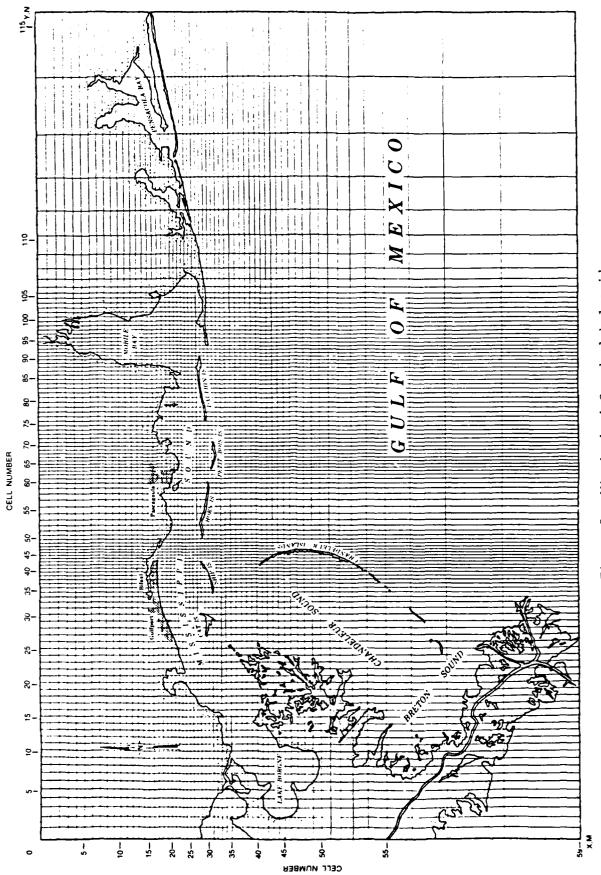


Figure 3. Mississippi Sound global grid

Lake Borgne were specified in a zone format. In this process, each succeeding step overrides the previous step values.

Table 3
Initial Salinity Conditions on the Global Grid

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Water Depth ft	Initial Salinity Value, ppt
0-10	22.0
10-20	23.0
20-30	25.0
30-50	30.0
50-75	34.0
75-100	34.3
100-120	34.5
120-200	35.0
200-300	35.5
300-500	36.0

Salinity Grid-Cell-by-Grid-Cell Interpolated Limits

	Global Grid	Cell Range
<u>Patch</u>	N	<u>M</u>
1	15-27	19-39
2	28-87	15-32

Salinity Zone Specified Initial Conditions

		l Grid Range	Salinity
Zone	N	<u> </u>	ppt
1	1-15	33-50	15

58. Salinity boundary conditions which remained constant over time are shown in Table 4. A cell-centered spatial interpolation similar to that employed for water surface elevations was used to determine salinity values along the seaward boundary.

Table 4
Global Grid Boundary Salinity Conditions

Tidal Signal	Global Grid Cell	Salinity Value, ppt
1 2 3 4 5	(115,58)	36
2	(115,56)	36
3	(115,50)	36
4	(115,37)	36
5	(115,22)	34
6	(31,59)	30
7	(42,59)	36
7 8 9	(57,59)	36
	(73,59)	36
10	(87,59)	36
11	(103,59)	36
12	(110,59)	36
13	(112,59)	36
14	(115,59)	36
Freshwater Inflow		
IIIIIOW		
1	(97,3)	0
2	(59,19)	24
2 3 4 5 6	(59,17)	24
4	(13,33)	15
5	(19,20)	17
6	(32,15)	23

- 59. Wind data reported by Raytheon Ocean Systems (1981) over the period are presented in Table 5. The spatially averaged wind speeds and directions shown were lagged 6 hr in order to investigate model sensitivity to wind. A constant drag coeffecient equal to 0.001 was used in the computations.
- 60. A total of 1200 time steps were used to simulate 120 hr of prototype time. Wind information input at 6-hr intervals was interpolated in time at each time step. Both salinity schemes were considered. The scheme 1 FCT results and the scheme 2 three time level results are shown in Table 6. The following previously calibrated effective dispersion coefficients are employed:

$$C_x = C_y = 10$$

$$D_{x} = D_{y} = 0$$

Reduction factor = 0.0388

Table 5 Wind Data for 20-24 Sep

										Average
Julian	GMT	_	MET 1	2.	MET 3	_	MET 4	_	MET 5	Speed/
Day	Hour	Speed	Direction	Speed	Direction	Speed	Direction	Speed	Direction	Direction
	24	6.4	123	12.5	110	9.1	114	12.0	103	9.6/112
797	9	4.3	156	4.6	154	7.4	162	12.8	156	7.3/157
	12	4.1	154	3.4	97	3.1	122	10.3	100	5.2/105
	18	5.1	135	8.3	152	7.4	142	7.6	134	7.6/141
	54	4.7	145	8.9	156	4.5	157	7.3	152	5.8/152
265	9	4.7	141	9.3	148	7.8	142	13.3	163	8.7/148
	12	6.1	192	3.7	195	3.2	160	9.9	138	4.9/171
	18	4.8	130	8.1	158	6.5	135	9.9	144	6.5/142
	24	5.8	153	0.6	153	6.3	160	7.9	168	7.2/158
266	9	11.1	167	8.1	160	5.0	163	8.1	153	8.0/161
	12	7.1	176	4.0	184	3.7	162	7.3	148	5.5/167
	18	9.4	153	7.0	170	0.9	102	6.2	143	5.9/142
	24	6.9	154	8.9	165	9.9	167	8.0	177	7.6/166
267	9	7.0	172	6.4	181	3.0	164	3.8	171	4.6/172
	12	3.4	35	6.2	357	2.8	15	1.4	31	3.4/27
	18	4.7	123	8.7	147	9.1	87	3.9	11	6.6/108
	24	5.6	159	7.5	163	5.7	162	8.2	157	6.7/160
268	9	8.2	180	8.9	176	5.1	166	9.6	158	7.4/170
	12	2.9	147	4.1	73	3.7	161	6.2	166	4.2/137
	18	3.6	188	8.3	184	4.5	238	4.3	193	5.1/201
	24	5.2	154	7.5	156	5.4	145	8.9	156	6.7/153
Note:	MET 2 wa	was nonfur	nonfunctioning this	is period					Z	
	3		are "land"	stations.					° (
	MET 4 ar	and MET 5	are "island"	"stations	ıs.			W 2700.	000	[±
	Speed (Arn) Direction (Speed (mrm). Direction (Magnetic)	etic)					7		
	17777117		. (, , , ,)°(

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Table 6
Global Grid Wind Sensitivity Simulation

T	01-1-1	20/21 S	ep 1980	24	Sep 1980	.4.4
Transect Station	Global Grid Cell	Measured	Initial Condition	Measured	Compu 1	2
Station	orra cerr	Heasured	Condition	Heasured		
T26	(15,39)	16.0	16.0	14.2	19.8	20.2
T30	(16,35)	17.0	17.0	17.2	17.4	18.4
T28	(16,38)	17.3	17.0	15.1	17.8	17.9
T32	(18,33)	17.5	17.0	17.6	17.8	17.8
T24	(18,38)	19.2	19.0	19.3	20.2	20.0
T34	(20,31)	19.2	19.0	19.5	19.3	19.4
T22	(21,35)	23.7	24.0	21.8	23.7	24.1
T36	(23,29)	21.8	22.0	21.1	21.3	20.7
T20	(24,33)	24.9	25.0	24.1	25.3	25.3
T38	(26,29)	22.0	22.0	23.1	22.2	25.8
T40	-					
	(27,24)	22.4	22.0	21.0	22.3	22.4
T18	(27,33)	26.8	27.0	25.7	24.4	23.3
T42	(29,26)	23.7	24.0	23.0	23.1	23.1
T6	(29,20)	24.0	24.0	23.8	24.1	24.1
Т8	(31,23)	24.8	25.0	23.9	25.0	25.2
T10	(32,26)	25.6	26.0	25.0	24.9	25.0
T12	(33,29)	27.3	27.0	25.5	25.5	25.5
T4	(34,23)	25.2	25.0	23.9	24.5	24.3
T14	(34,31)	28.3	28.0	27.1	25.5	24.4
T16	(34,32)	28.3	28.0	26.8	26.1	26.0
Т2	(40,27)	26.1	26.0	25.6	26.1	26.4
T44	(49,21)	23.6	24.0	23.4	25.2	25.3
T46	(49, 24)	26.9	27.0	26.2	25.9	25.5
T48	(49,27)	28.2	28.0	27.8	27.3	28.1
T50	(49,29)	28.3	28.0	28.7	27.4	27.2
T52	(53,25)	26.3	26.0	26.7	26.1	26.1
T54	(57,28)	27.3	27.0	27.6	28.9	28.9
Т64	(59,21)	27.7	28.0	27.5	27.6	28.4
T62	(60,23)	28.5	28.0	26.8	27.9	28.3
T66	(62,22)	27.3	27.0	27.7	26.9	26.7
T60	(62,24)	28.1	28.0	29.1	27.2	27.2
T58	(62,28)	29.1	29.0	29.6	28.2	28.0
T56	(62,32)	29.7	30.0	30.3	30.1	29.5
T68	(67,26)	27.9	28.0	27.5*	28.1	28.2
T70	(71,28)	28.4	28.0	29.9*	28.2	28.1
T74	(75,26)	28.1	28.0		28.4	28.3
T72	(75,20) $(75,30)$	28.7	29.0	28.5*	26.2	26.8
T76	(76,25)	26.6	27.0		28.2	28.1
T78	(81,25)	22.5	22.0		22.4	22.6
					22.6	22.9
T80	(86,25)	22.9	23.0		22.0	44.3

^{* 28} Sep 1980.

In regions of the Sound, the scheme 1 and scheme 2 results are nearly identical and are in agreement with the calibration simulation and measured salinity values. However, in the vicinity of the upper Mobile Bay freshwater inflow, the results diverge as shown in Table 7. The scheme 1 results are nonnegative and exhibit no oscillations. The scheme 2 results exhibit oscillations behind the freshwater front.

Refined Grid Results

- 61. In order to investigate the salinity distribution in the vicinity of the Pascagoula Channel, the refined grid shown in Figure 4 was developed. This grid employs $49 \times 28 = 1372$ cells. Maximum spatial resolution of 300 ft is employed to represent the navigation channels. The configuration of the channel system is idealized in the grid in order to reduce the number of grid cells. A 60-sec time step was used, resulting in a maximum spatial Courant number of less than 8 within the grid system.
- 62. The 20-24 Sep 1980 period with 6-hr lagged wind considered on the global grid was studied on the refined grid. The salinity values computed in the global grid scheme 1 FCT simulation were saved and interpolated temporally and spatially to provide the boundary conditions for the refined grid simulation. Initial conditions over the refined grid were determined from transect data and input cell by cell. Zero salinity values for the Pascagoula River System were input for cells (8,1) and (16,1) in order to establish a freshwater front.
- 63. A time step of 60 sec was employed 7200 times in order to simulate 120 hr of prototype time. Wind information input at 6-hr intervals from Table 5 was interpolated in time at each time step. The scheme 1 FCT scheme was selected based upon its superior performance on the global grid. Wind lagged simulation results using the calibrated effective dispersion coefficients in paragraph 60 are nearly identical to the calibration simulation results and correspond to measured values as shown in Table 8. In order to obtain an estimate of the freshwater influence and movement of the front, the salinity field at the end of the simulation is shown in Table 9. Note the scheme 1 results are nonnegative and exhibit no oscillation. The flow pattern in the vicinity of the freshwater inflow at (16,1) is extremely complex. The averaging processes employed in coupling the two time level scheme 1 FCT with

Table 7 Upper Mobile Bay Simulation Results in the Global Grid After 120 Hr

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Scheme 1 (Flux Corrected Transport)

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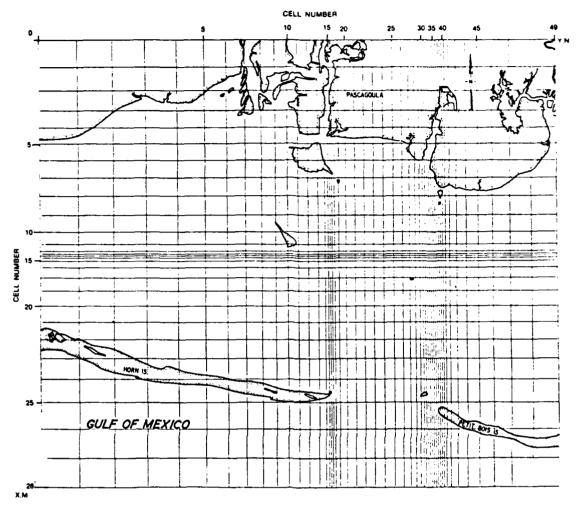


Figure 4. Pascagoula Channel System refined grid

Table 8
Refined Grid Wind Sensitivity Simulation

		20/21	Sep 1980	24 Se	
Transect Station	Refined Grid Cell	Measured	Initial Condition	Measured	Computed Scheme 1
T54	(8,22)	27.3	27.0	27.6	28.8
T64	(17,6)	27.7	28.0	27.5	28.3
T62	(24,9)	28.5	29.0	26.8	27.7
T66	(31,7)	27.3	27.0	27.7	27.9
T60	(33,7)	28.1	27.0	29.1	27.8
T58	(36,23)	29.1	29.0	29.6	27.7
T56	(34,26)	29.7	30.0	30.3	28.0
T68	(49,19)	27.9	28.0	27.5*	28.0

^{* 28} Sep 1980.

Table 9

Pascagoula River Vicinity Simulation Results After 120 Hr on the Refined Grid

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the three time level hydrodynamics may contribute to the unusual distribution over cells (15-17,1). These effects are usually local and the two time level scheme 1 FCT resolves the edge of the freshwater front. Additional research is warranted to flux-correct scheme 2 thereby eliminating the above averaging of hydrodynamic variables necessary in scheme 1.

64. The input data for this simulation are presented in Appendix C. Typical output from the salinity computations embodied within WIFM is shown in Appendix D.

Computer Requirements

65. The resources required for both the hydrodynamics and the salinity computations are shown in Table 10. Scheme 1 is more accurate but requires nearly three times more computer time than does scheme 2. In general a very large scientific computation oriented machine should be utilized for applications employing the number of cells in the Mississippi Sound study.

Table 10
CRAY 1-S Requirements

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66. The job control language (JCL) for a global grid and refined grid simulation is presented in Appendix E. It should be noted that the JCL shown is for the CRAY I-S Cray Operating System 1.09 as implemented at Kirtland Air Force Base, New Mexico.

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APPENDIX A: SUBROUTINE LISTINGS

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APPENDIX B: WIFM-SAL INPUT REQUIREMENTS

Card Group (Format)		Variable	Description
1 (16I5)	Required	NDTAP	Input tape unit
1a (8A8)	Required	ITL	Identification title card, up to 64 character, the 1st 8 are the plot identification
2 (1615)	Required	NMAX	Horizontal grid dimension (i.e., number of cells in the ndirection)
		MMAX	Vertical grid dimension, number of cells in the m-direction
Restart conditions: boundary imput table hot start conditions geometry and boundar in; n, u, and v been saved	es <u>ARE NOT</u> read in s: <u>INITL</u> = 0 sys cy input <u>MUST</u> be	n tem read	0initial condition 1restart conditions (omit card groups 6, 13-18, and 23) -mas for 0, but saves restart data every m tau
been saved		IOVER	Control variable 1simulation Oreads input only
		IFLVL	Oflow formulation 1velocity
		LEVEL	Number of time levels
		ISURG	<pre>0tidal circulation 1storm surge-horizontal coastline 2storm surge-vertical coastline</pre>
		IFETR	Ono feathering of tidal eleva- tion, boundary elevations, and freshwater discharges 1feathering of the above quantities
		ІНОТ	<pre>0normal run -1hot start information previously saved for η,u,v initsal con- ditions on logical unit 2 will be used nsave hot start conditions at itime = n on logical unit 2! Note η is surface elevation u is x-component of velocity</pre>
			<pre>v is y-component of velocity itime is the number of time steps elapsed</pre>

Card Group (For	mat)	Variable	Description
2a (3I5,2F10.0)	Required	ISAL	1salinity simulation 0not simulating salinity
Use a blank card for this group when you are not simulating salinity		ISALS ISALC	<pre>1FCT scheme 23 Time Level Explicit Scheme number of time steps into the simulation, when salinity starts</pre>
			Maximum salinity concentration allowable, in ppt. If CMAX is exceeded, error message is output
		XMS	Scale factor by which salinity concentrations are multiplied for printout (dimensionless)
3 (16I5)	Required	ITID	Number of entries in tidal input table or flow input table
		JTID	Number of t's between entries in the tidal or flow input tables. Note: if tidal constituents are used, set ITID equal to the number of t's in the tidal scenerio. Set ITJD = 1. Cannot mix con- stituent or tabular entries.
		NTID	Number of distinct tidal inputs (total number)
		NFLO	Number of distinct discharge input (total number)
	Pertains only to velocity grid	NP1 NP2 NP3	These are print controls for the output gridgrid is printed from N = NP1 to N = NP2 in steps of NP3 NP1 and NP2 are horizontal indices All vertical values for each N NP3 is the increment
		NPR	Overrides NP1,NP2,NP3 2print full grid of η only -2print full grid for η,u,v 1print from NP1 to NP2, η only -1print from NP1 to NP2, η,u,v
		MPR	Additional print control 1print flag arrays only -1print flag arrays, flood, barrier, and tidal or flow data 2print flag arrays, depths, and Chezy -2print all
		MSURF	Counter Prints surface elevation and discharge in increments of the values of MSURF

Card Group (Format)			Variable	Description	
	6I5) ontinued)				
				KS1,KS2,KS3,KS4 are flooding control	
			KSI	mhold cell face CLOSED for mτ's	
			KS2	mhold cell face OPEN for mt's	
			KS3	mhold SUBMERGED barrier charac- teristic for mī's	
			KS4	mhold OVERTOPPING BARRIER charac- teristic for mt's	
			KS5	Leave blank, not used at present	
			KS6	mupdates wind routine every mt's	
3a (16I5)		Required	NCON	Number of tide gages for which tidal constituents must be specified	
			NGLOB	Number of global grid tidal bound- ary signals used for cell-centered interpolation along the refined grid boundary	
			NTI	Number of tidal boundary signals used for cell-centered interpolation along the seaward boundary	
3b (16	15)	Optional	IGX _í	Location expressed in m (grid coordinate) for <u>each</u> tidal signal, i = 1,NT	
	NT = NTI + NGLOB Omit if NT = φ		${\tt IGY}_{\dot{\bf i}}$	Location expressed in m (grid coordinate) for <u>each</u> tidal signal, -i = 1,NT	
3с	Use only if NCON.GT.ф		IYEAR	Start time of simulation	
			IMONTH	Start time of simulation	
	Omit if NCON.EQ. φ		IDAY	Start time of simulation	
			IHR	Start time of simulation	
3d (37	I1) Omit if NCON.EQ.φ		ICONST	Refers to array NCONST which contains 37 constituents. To choose how many constituents you wish to consider, code this variable 1consider 0skip	
3e (16	I5) Omit if NCON.EQ.φ		NC j	j varies from 1 to NCONT where NCONT is the element number of the specific constituent you want con- sidered from array NCONST	

Card Gro	oup (Format)	Variable	Description	
4 (8F10.0)	Required	TAU	Time step length, i.e. Δt (sec)	
Note:	See IXPAN in card group 5 Code DX and DY. 1 map inc = X number of feet when	/*DX	Vertical spatial stepsize (minimum stepsize for α space) from map scale use 1 in. = ft	
Example:	card group 6 will be utilized Map scale 1:40000	/*DY	<pre>Horizontal spatial stepsize (ft) 1 in. = ft</pre>	
	CX = 3333.	G	Acceleration of gravity set to 32.2 (ft ² /sec)	
		ALAT	Average latitude of the study region, + for Northern hemisphere (•) - for Southern hemisphere	
		ΧΙ	Constant rate of rainfall (inches, day)	
		WA	Constant wind velocity (no N/S wind) -1variable wind as a function of time only. (Note: card group 11 is needed to complete wind information) -2variable wind as a function of space and time. (Provided by subroutine FETCHW.) (Note: omit card group 11)	
		ТНЕТА	Constant wind direction in degrees Use meteorological definition, i.e. NORTH is 0° EAST is 90° SOUTH is 180° WEST is 270° or the number of hours between entries of wind table if WA = -1	
		EPSD	ϵ_{d} is minimum amount of water defining a dry cell (in feet)	
		APSD	ϵ_{b} is minimum amount of water over a barrier for submergence (in feet)	
		DCON1 NVGD 1 MLW	Value to add to water depths to translate them to the model datum which is usually NVGD datum (in feet). Depths are negative, thus a - DCON1 will deepen	
		*DMPX	Value of land elevation assigned artificially to areas that will never flood (in feet) control value to cutoff, depth checking within WIFM; i.e., this is the MAX land elevation digitized	

 $^{^{\}star}$ Related to XLAND as follows: DMPX is used in digitizing the grid--XLAND < DMPX defines <u>highest</u> potential flood level elevation.

Card Gr	oup (Format)	Variable	Description	
4 (8F10.0) (Continued)		ROTA	Angle of x-axis as measured counterclockwise from EAST = 0° (in degrees)	
		TPRO	Start of prototype time for beginning of run (i.e., time of day in hours)	
		ADV	Ono advective or viscosity terms 1include advective terms, linearize at boundary 2include advective terms, use approximation at closed bounds	
		VIS	εviscosity coefficient multi- plier; it is dimensionless and if equal to φ omits the viscosity coefficient usually set to 1 for initial runs	
Note:	XLAND < DMPX defines maximum potential flood level elevation	NVGD n o	A value of h (i.e., land or water bottom elevation with respect to NVGD datum); greater than XLAND defines a cell that will never flood (in feet) XLAND > 0	
		XSCOUR	A value of h < XSCOUR defines a cell that will never go dry (feet) 0 < XSCOUR	
		SMAX	If η > SMAX , cease computation and print η (η is surface elevation) (ft)	
		SINIT	Set η = SINIT as initial conditions (normally Q). Note: SINIT = 999, the code will compute inverted barometer effect (ft)	
		DMAXG	Positive bound on maximum total water depth that will be experienced during simulation (in feet) (for control of length of friction table)	
		DCON2 NVGD - ms1	Value to add to tidal input values to translate them to model datum (NVGD) in feet	
		DLIMIT	Negative value serving as an artificial cutoff value on water depths (h) (negative since h < 0) in feet	
5	Required	MAXTIM	Number to t's to run simulation	
(16IS)		INTAP	msave η,u,v on logical unit l every mt -1no data is saved	

Card Group (Format)	-	<u>Variable</u>	Description
5 (16IS) (Continued)		IDELAY	Delay saving data on logical unit 1 until ITIME = IDELAY (Note: ITIME counts the number of time steps)
Note: Set these variables to zero; subroutines to	If these plug con-	IPLOT	<pre>≠0printer plots of elevation hydrographs will be made 0no plots</pre>
accomplish printer plots have been removed from the program, but can	trols are set to zero, omit card	IVPLOT	<pre>≠0printer plots of velocity mag- nitude hydrographs will be made 0no plots</pre>
be supplied upon District request	group 10	ICPLOT	<pre>≠0printer plots of peak surge elevation along the coast will be made 0no plots</pre>
		IXPAN	<pre>#0read in variable grid expan- sion coefficients in card group 6 which will be the output file from program GRID saved on tape 7 0indicates constant spatial step input this step size in card group 4 in DX and DY variables</pre>
		NGAGE	Number of locations where you want data saved, omit card groups 8 and 9 if NGAGE = 0 . Card group 8 is gage locations if NGAGE = 0 , NFREQ = 0
		NFREQ	Frequency to print hydrodynamics at gage points (every NFREQ τ 's)
		KREST	Start run at ITIME = KREST. Set to zero except for restart run
		NZP	Number of corrections to input depth grid; omit card group 14 if NZP = 0
		NZQ	Number of corrections to input coded friction grid; omit card group 16 if NZQ = 0
		MDTAP	Logical unit for depth and coded friction input data (normally 5)
		NTABLE	Length of wind input data; i.e., number of entries in the table
		IGLOB	nsave boundary conditions (on logical unit 25) from Global Grid at n points (cells) for later use as forcing conditions to an embedded grid (will need card group 29 to locate indices) 0no saving for later use

Card Group (Format)		Variable	Description
6 (4G20.11)	Optional	ANG	Dummy variable for the first value of GRID output
This group is created program GRID on tape 7 is omitted if IXPAN = or INITL = 1	and	YNU i	Expansion coefficients for n-direction (horizontal) of the variable grid = 1, NYY NYY = 2*NMAX (dimensionless)
		XNU _i	Expansion coefficients for verti- cal direction (indirect) of the variable grid i = 1 , NXX NXX = 2*MMAX (dimensionless)
7 (16I5)	Required	NPRINT	Time step index to print grid an array of 32 elements thus allowing up to 32 printouts (array must be filled, so two cards are required to satisfy the read)
8 (16I5) Omit if NGAGE = 0	Optional	NPOT _i	Horizontal indices of locations (i.e. gage) where you want data saved; location is expressed in terms of the horizontal dimension of the grid (N values) i = 1, NGAGE
•		$\mathtt{MPOT}_{\mathbf{i}}$	Vertical indices of gage locations (M values) i = 1 , NGAGE
9 (16I5) Omit if NGAGE = 0	Optional	IGAGE _i	Codes for methods of computing flows at gage points $i = 1$, NGAGE $1-u, \overline{v}$
$ \bar{v} = \frac{1}{4} (V_{n,m} + V_{n-1,m} + \bar{u}) = \frac{1}{4} (U_{n,m} + U_{n,m-1} + \bar{u}) $			2 \bar{u} , \bar{v} 3 \bar{u} , \bar{v} default $\begin{cases} \bar{v} = 4pt \text{ avg of } \\ v = at u \end{cases}$ $\begin{cases} \bar{u} = 4pt \text{ avg } \\ u = at v \end{cases}$
$\bar{u} = \frac{1}{2} (U_{n,m} + U_{n,m-1})$		V _{n,m}	4u,v 5u 6v
$\bar{v} = \frac{1}{2} (v_{n,m} + v_{n-1,m})$	U'n,m		7 u 8 v
10 (515,2F5.0) Omit <u>all</u> if: IPLOT = ICPLOT = and IVPLOT =	0		These groups are actually three different sets of variables, each set associated with a type of printer plot to control format of plots; variable list and descriptions are not included
			Subroutines have been removed from the code, but can be supplied upon District request

Card Group (Format)	-	Variable	Description
10a (16I5)	Optional		IPLOTcontroller for elevation hydrographs IVPLOTcontroller for velocity magnitude hydrographs ICPLOTcontroller for peak surge elevations (along the coast) plot
		4	Ref: card group 5
11 (16F5.2) Omit if WA NE-1	Optional	WAT _i	Variable wind velocity (mph) i = 1 , NWAT, NWAT = THETA (see group 4)
ref group 4		THT _i	Corresponding wind direction measured from North as THT (deg) i = 1, NWAT
12 (10E8.1)	Required	character	group codes terrain and barrier ristics. Each variable in this card 20 values
		XMAN ₁	Manning's coefficient for each code i (i = 1,20) used for defining friction (Note: value of code (1) is used for all water outside the computational boundaries). This array must be ordered in the same manner as the depth zones defined in card group 15. For examplelowest value to highest value of Manning's coupled with depth zones of deep to shallow (i is dimensionless)
		ZBi	Barrier height for each code i = 1,20 . This array is referenced by card group 17 variable INDX (ft)
		CB _i	Chezy coefficient to approximate a barrier of overtipping for each code $i = 1,20$ $(\sqrt{g}, ft^{1/2}, sec)$ $C_b = \frac{1.49}{n_b} (\epsilon_b)^{1/6}$
		$co_{f i}$	Admittance coefficient for over-
		•	topping barrier $(\sqrt{g}, ft^{1/2}/sec)$ usual range (3-5) i = 1,20
		CAYD _i	Recession coefficient for draining of flood cellkeyed by friction codes (fraction of water depth to be allowed to drain within one time step) i = 1,20

Card Group (Format)		Variable	Description
12 (10E8.1) (Continued)		CD _i	Admittance coefficient for limiting movement of water onto flood cellskeyed by friction codes $(\sqrt{g}, \text{ft}^{1/2}/\text{sec})$ usual range (3-5) $i = 1,20$
		CANPY1 i	
		canpy ₂ /	Canopy coefficients for flooding used to increase Manning's n friction coefficient over heavily vegetated marshes. (C_1 dimensionless) (C_2 is in feet) $\eta_c = \eta_b \begin{pmatrix} -d^2/C_2 \\ 1 + C_1 e \end{pmatrix}$ for $d < 5$ ft
			Set $C_1 = 0$, and $C_2 = 1$ for nonuse. $i = 1,20$
13 (10F8.0) Omit only if INITL.EQ.	Required	TMP _n	Depth grid array; depths at center of each grid cell. For row M of depths n = 1 , NMAX, start a new card for each M: units of measure (ft) negative in sign
13a	Optional	Include o	only if ISAL ≠ 0
(16I5)		IDEPTH	Number of depth intervals employed to interpolate initial salinity condition based upon depth
		IFIELD	Number of patches in which initial salinity conditions will be input on a cell-by-cell basis
		IZONE	Number of zones in which the initial salinity condition will be a constant
		Include i	f IDEPTH ≠ 0
13b (16F5.1)	Optional	$TMP_{\mathbf{N}}$	Salinity initial value array, N = 1 , IDEPTH (ppt)
		D(N,1)	Depth value array, N = 1 , IDEPTH + 1 (ft)
13c (16I5)	Optional	Repeat IF IFIELD ≠	TELD times. Include only if
		NL	Lower horizontal limit of patch i (n-coordinate of cell)
		NU	Upper horizontal limit of patch i (n-coordinate of cell)
		ML	Lower vertical limit of patch i (m-coordinate of cell)

Card Group (Format)	 -	Variable	Description
13c (16I5)		Mu	Upper vertical limit of patch i (m-coordinate of cell)
(Continued)			Repeat (ML - MU) + 1 times
(16F5.1)	CN(N,M),	N = NL,NU	Initial salinity concentration (ppt)
Omit only if INITL.	Required EQ.1		Card groups 13d and 13e are ref. Subroutine CONST to read in five different sets of values for the following conditions:
13e			CNinitial salinity values (in ppt) required only for IZONE \$\neq 0\$ CXdispersion factor in the X-dir (dimensionless) DKXXdispersion offset in the X-dir (ft^2/sec) CYdispersion factor in the Y-dir (dimensionless) DKYYdispersion offset in the Y-dir (ft^2/sec)
		The varia	bles for the card group are:
(4I5,F10.0)		NZ	Number of zones covering the grid lst card
(4I5,F10.0)		NL	Lower horizontal index of zone 2nd card
		Nu	Upper horizontal index of zone
		ML	Lower vertical index of zone
		MU	Upper vertical index of zone
		R	Value of CN, CX, DKXX, CY, or DKYY to be read in. This is a single value for the set of cells defined N = L,u , M = L,u ; i.e., cells (N,M) where NL ≤ N ≤ Nu and ML ≤ M ≤ Mu
			e two cards of this group until all condition variables above are
14 (215,F5.1)	Optional	N	Corrections to individual cell depths Horizontal index of cell
Omit if NZP.EQ.Ø or	INITL.EQ.1	M	Vertical index of cell
		DNM	Corrected depth of cell (ft) negative in sign, digitized depth without model datum correction, usually reference is nautical charts, MLW or MLLW Gulf Coast Datum

Card Group (For	mat)	Variable	Description
15 (3512)	Required	N	If $N = 77$, the next card begins the friction codes for all cells in the grid
	, or 15a alternate nless INITL = 0		If N ≠ 77, subroutine FRICTN is called. N is the number of depths used to develop the friction codes and the card which follows begins the definition of depth ranges
		Within Sl	UBROUTINE FRICTN
	sign a Manning's	DP _i	Depths to define ranges of depths which correspond to the Manning's n in the XMAN array, used to develop the friction codes (see group 12)
n based on dept			i = 1, ND (Note: N = ND and LE.21)
Omit if INITL.	5Q. 1		DA's are negative values and must be put in the same relative order as the values of Manning's n in XMAN. (Note: deep to shallow if lowest to highest is the order of Manning's n) (ft)
15a (3512)	Required	used. Th	group if SUBROUTINE FRICTN is <u>not</u> is alternate group 15a is the frices and is related to card group 12
In this group to operates to all assign the Mann	low you to	ITIDE _M	This variable is read within a DO LOOP where N = 1,NMAX M = 1,MMAX
Omit if INITL.	EQ. 1		ITIDE is a number for each cell in the grid between 1 and 20 corresponding to the elements of array XMAN which you wish to assign to each cell. The loops operate to assign values by columns
16 (415) Omit if NZQ.EQ.	Optional .0 or INITL.EQ.1	N	Used for corrections to <u>coded</u> friction grid for individual cells Horizontal cell index
		М	Vertical cell index
		MAN(N,M)	Number 1 to 20 to correspond to the elements of array XMAN desired

The code sets up flag areas (internal flags) for each $\,u\,$ and $\,v\,$ cell face (see diagram following) in the grid based upon depth field and advection code (ADV is set equal to 0, 1, or 2).

Card Group 17 provides for establishing the codes for boundary flags and card group 18 provides for correction to the internal flags.

Card Group (Format)	Variable	Description
17a Required (312,614) Omit only if INITL.EQ.1	ITYP	Barrier type codes 1exposed barrier at all times 2overtopping barrier 4submerged barrier 8tidal input 9flow input 99exit this group of input, leave remainder of card blank UNLESS you wish to make cor- rections to the ICU and ICV flag arrays then leave INDX and IDIR blank and set I1 ≠ 0 and include card group 18. It should be set to the number of corrections to be made
	INDX	Value is from 1 to 20, keyed to element of array ZB in card group 12 to set barrier heights if ITYP is set to 1, 2, or 4 For ITYP set to 8, value is from 1 to NTID (NTID is the total number of tidal input signals), i.e., identifies which tidal input
		For ITYP set to 9, value is from 1 up to NFLD to identify which flow input
O ₁ (N,M) v face u face	IDIR	1flow direction is through u cell space 2flow direction is through v cell face
м,х	11 12 13	Locator grid indices for barrier, tidal input, or flow input For a u face feature: Il is the row (M) I2 is the beginning column (N) I3 is the ending column (N) For a v face feature: I1 is the column (N) I2 is the beginning row (M) I3 is the ending row (M)

Card Group (Format)		Variable	Description
17a (312,614) (Continued)		14	Used with tidal or flow input only, otherwise leave blank Oinput directed toward the right or bottom of the grid 1input directed toward the left or top of the grid
		15 16	When used ITYP = 8 , INDX = 1 Used for tidal input only when you want to interpolate the values for the tidal input boundary between two tidal signals. I5 and I6 correspond to the two tidal signal numbers; i.e., the elements numbers (of your 2 signals) in the tidal signal arrays IGX and IGY
17b (F8.0) Include if ISAL ≠ 0	Optional	XDL	Dispersion coefficient reduction factor for flow restriction (dimensionless)
18 (415) Omit unless ITYP.EQ.99.AND.I1.NE.	Optional		Correction codes to ICU, ICV flag arrays. This read statement is in a loop which will execute I1 num- ber of times
		N	Horizontal index of cell
See description at ITY INDX codes above	TP and	M	Vertical index of cell ICU _{N,M} a 2 digit code, n ₁ n ₂ , where n ₁ is ITYP and n ₂ is INDX of the specific u face of cell (N,M) ICV _{N,M} same except v face condition is described by n ₁ n ₂
19 (415,F5.0)	Required		This card group is a special application: NBGset equal to 0 KSHFTset equal to 1
		NBG	0normal
			 -1no tidal input or discharge, used for storm surge
		KSHFT	Time index unit, where the simulation begins in the boundary input tables; i.e., time step index for beginning of input used with HOTSTART CONDITIONS
20	Optional	TITLE	Gage title
(4Ab, 3F10.0) (7) Omit if NT10 = 0	Tidal inputs)	TLON	Longitude in degrees of gage
or NCON = 0 or		TM	Time meridian in degrees
NBG = -1		но	Mean value referenced to model datum

Card Group (Format)	_	Variable	Description
20a (8F10.0) Use only with 20	Optional	HM _{j,i}	Tidal amplitude for each of the tidal constituents j = 1,NCONT (NCONT is the element of the array NCONST which holds the values of the tidal constituents) i = 1,NTID (number of tidal inputs) that is, HM is the specific tidal amplitude in feet of each constituent identified by its element number in the array NCONST for each of the distinct tidal inputs
		KAPPA _{j,i}	Tidal phases of the constituents as above (in degrees)
20b (15F5.2) These card groups are boundary INPUT, thus		ssv _j	Tidal elevation for each time step j = 1,IT (IT = ITID (card group 3) the number of entries in the tidal input table)
if NTID = 0		XKQ	Shift in time step units
		ALP	Amplitude multiplication factor
Repeat card group 201	b (NTID-NCON) t	imes. Omit	if NTID = NCON
NOTE: If you are sing additional groups re			O, you will need the following
20c (15F5.2)		ssv _j	<pre>j = 1,ITspecific salinity value for each tidal signal</pre>
21a	Optional	ssv _j	Discharge (in cfs) for each time
(15F5.2) omit if NFLO = These groups are flow		J	<pre>j = 1,IT where IT = ITID , number</pre>
		XKQ	Shift in time step units
		ALP	Multiplication factor
Repeat this card gro	up for each flo	w input	
If ISAL.NE.O you wil	l need group 21	a repeated	for each flow input as well
21b (15F5.2)	Optional	ssv _j	<pre>j = 1,IT , specific salinity value for each flow input (NFLO)</pre>
22	Optional		Specify if IFETR ≠ 0
(F5.0,I5)		XLEVEL	Feather level for tidal elevation
		NTD	Number of time steps for flow input feathering

ently not being unitput. Supplied of JNS	tilized. Subroutines have been re- upon request.
JNS	
	Number of ranges for computing volumetric discharge (if equal to 0 put in a blank card for this group) integrated value
ange JT1	Time index marking beginning of discharge computation (time step)
JPER	Period of discharge cycle in time index units (total length of cycles in time steps)
JDT	Sampling time step in time index units
JMUL	Number of seconds in sampling period (τ JDT)
JDELAY	Delay print of special gage data until ITIME = JDELAYS (avoid spinup time computation)
ional JDIR	Direction of flow in discharge range. Coded: 1vertical direction 2horizontal direction where i = i,JNS
$\mathtt{JMN}_{ extbf{i}}$	Coordinate index of the range line i = 1,JNS
JMN1 _i	Range line extends from JNS1 to $JNS2_{\dot{1}}$
JMN2 i ∫	where i = 1,JNS
uired MNPOT	Number of special gage points to be punched and/or plotted for surface elevation data
MSKP	Frequency to punch surface elevation data (i.e., every MSKP t's)
MDLY	Delay punch of surface elevation data (at special gage points) unti
NVELPN	Number of special gage points for punching and/or plotting velocity magnitude
MVELP	Frequency to punch velocity magnitude data (every MVELP τ 's) (τ is time step)
MVDLY	Delay punch of velocity data until
	JPER JDT JMUL JDELAY ional JMN1 JMN2 MNPOT MSKP MDLY NVELPN MVELP

These control variables are for tape (punch) or plot output and are output to tape 3. The plotting is automatic. Plot file name must be specified in JCL.

Card Group (Format)	_	Variable	Description
26 (16I5) Omit if NNPO7.EQ.Ø	Optional	INPOT	N indices of special gage points for surface elevations data (ref. card group 25) $i = 1$, NNPOT up to a maximum of 30 pts
		${\tt JMPOT}_{f i}$	M indices of same (start a new card) i = 1,NNPOT
27 (16I5) Omit if NVELPN	Optional	NVCORD	N indices of special gage points for velocity magnitude data i = 1, NVELPN
EQ.Ø		${\tt MVCORD}_i$	M indices of same (start new card) i = 1,NVELPN
28 (16I5) Omit if ISURG = 0 (see card group 2)	Optional	COAST	Indices of open coast cells where i = 1,NMAX for horizontal coast-line and i = 1,MMAX for vertical coastline. This information is obtained from program SHORE
29 (16I5) Omit if IGLOB = 0	Optional	IU1 _i	N indices of cells where boundary conditions are to be saved in global grid, i = 1,IGLOB
(see card group 5)		IU2 _i	M indices of same i = 1,IGLOB (start a new card)

APPENDIX C: REFINED GRID INPUT DATA

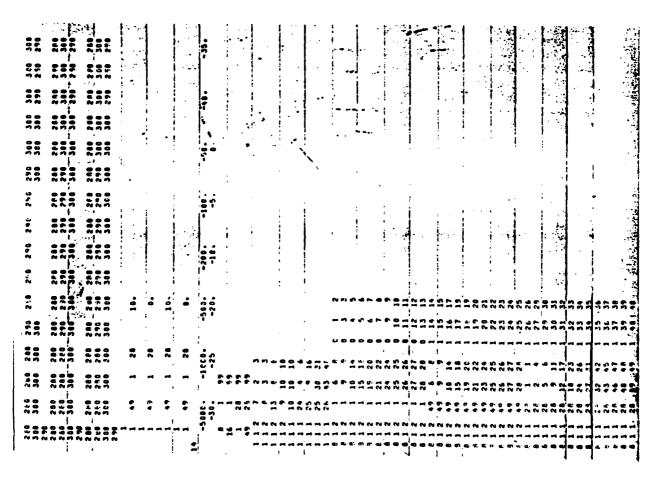
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APPENDIX D: REFINED GRID OUTPUT DATA

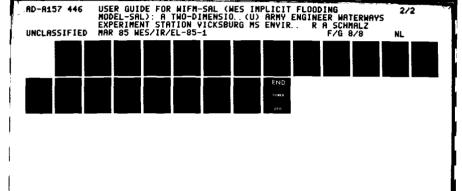
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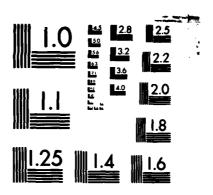
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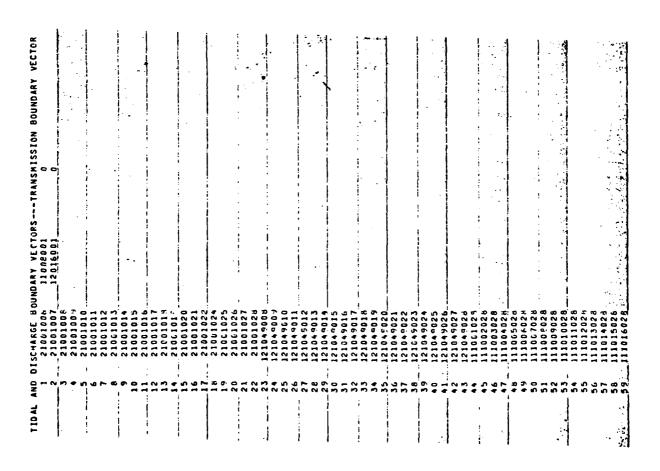
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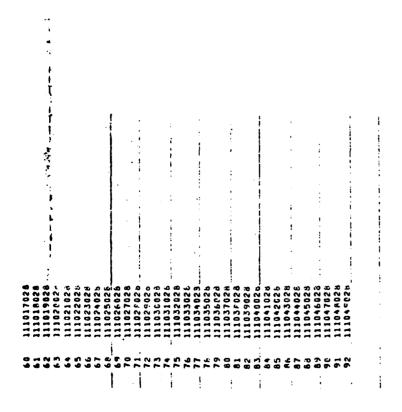
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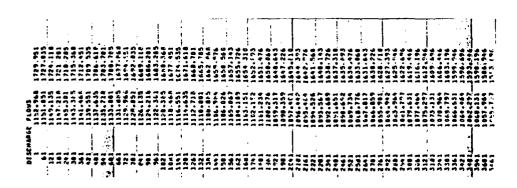
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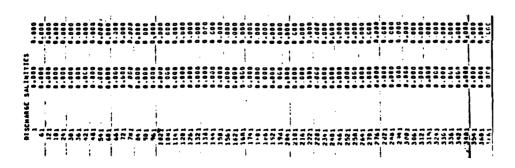
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APPENDIX E: CRAY I-S JOB CONTROL LANGUAGE

Global Grid Hydrodynamics and Salinity

```
COESR, T17, I060, STCRA.
ACCOUNT(H48511KV00,921C0933-ACO,ACOCOE,6343809)
JOB, JN=COESR, T=120.
SWITCH, CARET=+.
ACQUIRE, DN=$PL, PDN=SFMSHYDDU, RT=0, MF=11, UQ, ID=COFHO933.
UPDATE, C=DATA, E, DW=80, IN.
DELETE, DN=$PL, NA.
RELEASE, DN=$PL.
ACQUIRE, DN=$PL, PDN=CLMSHYDPU, RT=0, MF=11, UQ, ID=COEH0933.
UPDATE, C, F, IN.
DELETE, DN=$PL, NA.
RELEASE, DN=$PL.
AUDIT, PDN=-, ID=COEHO933.
CFT, I=$CPL.
REWIND, DN=DATA.
COPYSBF, I=DATA, O=$OUT.
REWIND, DN=DATA.
ASSIGN, DN=DATA, A=FTO5.
LDR, MAP, LIB=DISSPLA.
REWIND, DN=FT07: FT08: FT09: FT10: FT11: FT12.
COPYD, I=FT07.
COPYD, I=FT08.
COPYD, I=FT09.
COPYD, I=FT10.
COPYD, I=FT11.
COPYD, I=FT12.
DISPOSE, DN=FT99, SDN=COETGS1PLOT, ID=COEHO933, DF=SB, DC=ST, WAIT.
DISPOSE, DN=FT25, ID=COEHO933, DC=ST, DF=TR, WAIT, +
TEXT='USERNO,868,XUMPOM.MASS.STORE FT25:TINSH1.'.
DISPOSE, DN=FT35, ID=COEHO933, DC=SI, DF=TR, WAIT, +
TEXT='USERNO,868,XUMPOM.MASS STORE FT35:TINTS1.'.
EXIT.
REWIND, DN=FT07: FT08: FT09: FT10: FT11: FT12.
COPYD, I=FT07.
COPYD, I=FT08.
COPYD, I=FT09.
COPYD, I=FT10.
COPYD, I=FT11.
COPYD, I=FT12.
DISPOSE, DN=FT89, SDN=COETGS1PLOT, ID=COEHO933, DF=SB, DC=ST, WAIT.
DISPOSE, DN=FT25, ID=COEHO933, DC=ST, DF=TR, WAIT, +
TEXT='USERNO,868,XUMPOM.MASS STORE FT25:TINSH1.
DISPOSE, DN=FT35, ID=COEHO933, DC=ST, DF=TR, WAIT,+
TEXT='USERNO,868,XUMPOM.MASS STORE FT35:TINTS1.
```

Refined Grid Hydrodynamics and Salinity

```
COESR, T17, 1060, STCRA.
ACCOUNT (H48511KV00,921C0933-AC0,AC0C0E,6343809)
JOB, JN=COESR, T=820, CL=C.
SWITCH, CARET=+.
ACCESS, DN=FT24, UQ, NA.
ACCESS, DN=FT34, UQ, NA.
DELETE, DN=FT24, NA.
DELETE, DN=FT34, NA.
RELEASE, DN=FT24.
RELEASE, DN=FT34.
ACQUIRE, DN=FT24, ID=COEH0933, RT=0, DF=TR, UQ,+
TEXT='USERNO,868,XUMPOM.MASS.GET FT24:TINSH.'.
ACQUIRE, DN=FT34, ID=COEH0933, RT=0, DF=TR, UQ,+
TEXT = 'USERNO, 868, XUMPOM. MASS. GET FT34: TINTS.'.
REWIND, DN=FT24:FT34.
ACCESS, DN=DATA, ID=COEH0933, UQ, NA.
DELETE, DN=DATA, NA.
RELEASE, DN=DATA.
ACQUIRE, DN=DATA, ID=COEH0933, RT=0, UQ, +
TEXT='USERNO,868,XUMPOM.MASS.GET DATA:H485TRSD.'.
ACQUIRE, DN=$PL, PDN=CLMSHYDPU, RT=0, MF=11, UQ, ID=COEH0933.
UPDATE, C, F, IN.
DELETE, DN=$PL, NA.
RELEASE, DN=$PL.
AUDIT, PDN=-, ID=COEH0933.
CFT, I=$CPL, L=0.
REWIND, DN=DATA.
COPYSBF, I=DATA, O=$OUT.
REWIND, DN=DATA.
ASSIGN, DN=DATA, A=FT05.
LDR, MAP, LIB=DISSPLA.
REWIND, DN=FT07: FT08: FT09: FT10: FT11: FT12.
COPYD, I=FT07.
COPYD, I=FT08.
COPYD, I=FT09.
COPYD, I=FT10.
COPYD, I=FT11.
COPYD, I=FT12.
DISPOSE, DN=FT99, SDN=COERTSPLOT, ID=COEH0933, DF=SB, DC=ST, WAIT.
REWIND, DN=FT07:FT08:FT09:FT10:FT11:FT12.
COPYD, I=FT07.
COPYD, I=FT08.
COPYD, I=FT09.
COPYD, I=FT10.
COPYD, I=FT11.
COPYD, I=FT12.
DISPOSE, DN=FT99, SDN=COERTSPLOT, ID=COEH0933, DF=SB, DC=ST, WAIT.
```

END

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